

量子力学 B

2021 秋季学期

作业 9 (截止期: 12 月 8 号周三课上)

1. 设 $|\ell m\rangle$ 为力学量完全集 $\{\hat{\ell}^2, \hat{\ell}_z\}$ 的共同本征态, 其中 $\hat{\ell}, \hat{\ell}_z$ 分别为轨道角动量及其在 z 方向的分量, ℓ, m 为相应量子数。如果只考虑 $\ell = 1$ 的子空间, 请解答下述问题:

a. 请写出 $\hat{\ell}_y^2$ 在此子空间内的矩阵表示, 并注明矩阵表示所用的基。

b. 如果在 $|\ell = 1, m = 1\rangle$ 态上测 $\hat{\ell}_y^2$, 可能的测值和相应的几率是多少?

c. 求 $\langle \ell = 1, m = 1 | \hat{\ell}_y^2 | \ell = 1, m = 1 \rangle$ 。

2. 证明:

a. $\{\sigma_i, \sigma_j\} = 2\delta_{ij}$

b. $\sigma_i \sigma_j = \delta_{ij} + i\varepsilon_{ijk} \sigma_k$

c. 设 $\sigma_0 = I$, 则任意 2×2 矩阵 M 均可以写做 $M = \sum_{i=0,x,y,z} M_i \sigma_i$, 证明 $M_i = \frac{1}{2} \text{Tr}(M \sigma_i)$ 。

3. 请把 $e^{i\lambda \hat{\sigma}_\alpha} \hat{\sigma}_\alpha e^{-i\lambda \hat{\sigma}_\alpha}$ ($\alpha = x, y, z$) 表示成单位阵和 Pauli 矩阵的线性组合。

4. 假设某粒子自旋初态为 z 方向自旋的本征态 $|\downarrow\rangle$ 。从 0 时刻到 t 时刻, 体系的 Hamiltonian

为 $\hat{H}_I = A\hbar \hat{\sigma}_x$; 从 t 时刻到 $t + \tau$ 时刻, 体系的 Hamiltonian 为 $\hat{H}_{II} = \frac{1}{2} \hbar \omega (\hat{\sigma}_z + 1)$; 从

$t + \tau$ 时刻到 $2t + \tau$ 时刻, 体系的 Hamiltonian 为 $\hat{H}_I = A\hbar \hat{\sigma}_x$ 。试求在 $2t + \tau$ 时刻测量粒

子处在 $|\downarrow\rangle$ 的几率。

1. 设 $|lm\rangle$ 为力学量完全集 $\{\hat{l}^2, \hat{l}_z\}$ 的共同本征态, 其中 \hat{l}, \hat{l}_z 分别为轨道角动量及其在 z 方向的分量, l, m 为相应量子数。如果只考虑 $l = 1$ 的子空间, 请解答下述问题:

a. 请写出 \hat{l}_y^2 在此子空间内的矩阵表示, 并注明矩阵表示所用的基。

b. 如果在 $|l = 1, m = 1\rangle$ 态上测 \hat{l}_y^2 , 可能的测值和相应的几率是多少?

c. 求 $\langle l = 1, m = 1 | \hat{l}_y^2 | l = 1, m = 1 \rangle$ 。

解: 以 $\{\hat{l}^2, \hat{l}_z\}$ 的共同本征态作为基

由上次作业结论, 有

$$\hat{l}_+, \hat{l}_- \text{ 对应的矩阵为 } \begin{pmatrix} 0 & 0 & 0 \\ \sqrt{2} & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix} \hbar, \begin{pmatrix} 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \hbar$$

$$\text{由于 } \hat{l}_y = \frac{1}{2i} (\hat{l}_+ - \hat{l}_-)$$

则 \hat{l}_y 对应的矩阵为

$$\frac{\sqrt{2}}{2i} \hbar \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

则 \hat{l}_y^2 对应的矩阵为

$$\frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

所用的基依次为 $|1, -1\rangle$

$|1, 0\rangle$

$|1, 1\rangle$

b. 令 $\det \begin{vmatrix} \lambda - 1 & 0 & 1 \\ 0 & \lambda - 2 & 0 \\ 1 & 0 & \lambda - 1 \end{vmatrix} = 0$

得到 $\lambda_1 = 0, \lambda_2 = \lambda_3 = 2$.

相应的归一化本征态为 $|\alpha\rangle = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, |\beta\rangle = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, |\gamma\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

则可能的测值为0, \hbar^2 .

$$\text{测得为0的概率 } P(l_y^2=0) = \left| \frac{\sqrt{2}}{2} (-1, 0, -1) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{2}$$

$$\text{测得为}\hbar^2\text{的概率 } P(l_y^2=\hbar^2) = 1 - P(l_y^2=0) = \frac{1}{2}$$

$$c. \langle l=1, m=1 | \hat{l}_y^2 | l=1, m=1 \rangle$$

$$= (0, 0, 1) \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \frac{\hbar^2}{2}$$

2. 证明:

a. $\{\sigma_i, \sigma_j\} = 2\delta_{ij}$

b. $\sigma_i \sigma_j = \delta_{ij} + i\epsilon_{ijk} \sigma_k$

c. 设 $\sigma_0 = I$, 则任意 2×2 矩阵 M 均可以写做 $M = \sum_{i=0,x,y,z} M_i \sigma_i$, 证明 $M_i = \frac{1}{2} \text{Tr}(M \sigma_i)$.

证明:

$$a. \{\sigma_x, \sigma_x\} = 2 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_y, \sigma_y\} = 2 \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_z, \sigma_z\} = 2 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_x, \sigma_y\} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\{\sigma_x, \sigma_z\} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\{\sigma_y, \sigma_z\} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$b. \sigma_x \sigma_x = \hat{I} = \sigma_y \sigma_y = \sigma_z \sigma_z \quad \text{所以 } \sigma_j \sigma_j = \hat{I}$$

$$\sigma_x \sigma_y = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = i \sigma_z \quad \sigma_y \sigma_z = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = i \sigma_x$$

$$\sigma_z \sigma_x = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = i \sigma_y \quad \sigma_y \sigma_x = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = -i \sigma_z$$

$$\sigma_z \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = -i \sigma_x \quad \sigma_x \sigma_z = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = -i \sigma_y$$

$$\text{所以 } \sigma_i \sigma_j = \delta_{ij} + i \epsilon_{ijk} \sigma_k$$

$$c. \mu = \mu_0 \sigma_0 + \mu_1 \sigma_x + \mu_2 \sigma_y + \mu_3 \sigma_z = \begin{pmatrix} \mu_0 + \mu_3 & \mu_1 - i\mu_2 \\ \mu_1 + i\mu_2 & \mu_0 - \mu_3 \end{pmatrix}$$

$$\frac{1}{2} \text{Tr}(\mu \sigma_0) = \frac{1}{2} \text{Tr} \begin{pmatrix} \mu_0 + \mu_3 & \mu_1 - i\mu_2 \\ \mu_1 + i\mu_2 & \mu_0 - \mu_3 \end{pmatrix} = \mu_0$$

$$\frac{1}{2} \text{Tr}(\mu \sigma_x) = \frac{1}{2} \text{Tr} \begin{pmatrix} \mu_1 - i\mu_2 & \mu_0 + \mu_3 \\ \mu_0 - \mu_3 & \mu_1 + i\mu_2 \end{pmatrix} = \mu_1$$

$$\frac{1}{2} \text{Tr}(\mu \sigma_y) = \frac{1}{2} \text{Tr} \begin{pmatrix} \mu_2 + i\mu_1 & -i(\mu_0 + \mu_3) \\ i(\mu_0 - \mu_3) & \mu_2 - i\mu_1 \end{pmatrix} = \mu_2$$

$$\frac{1}{2} \text{Tr}(\mu \sigma_z) = \frac{1}{2} \text{Tr} \begin{pmatrix} \mu_0 + \mu_3 & \mu_3 + i\mu_2 \\ \mu_1 + i\mu_2 & \mu_3 - \mu_0 \end{pmatrix} = \mu_3$$

3. 请把 $e^{i\lambda \hat{\sigma}_\alpha} \hat{\sigma}_\alpha e^{-i\lambda \hat{\sigma}_\alpha}$ ($\alpha = x, y, z$) 表示成单位阵和 Pauli 矩阵的线性组合。

$$\text{解: } e^{-i\lambda \hat{\sigma}_z} = \cos \lambda \hat{I} - i \hat{\sigma}_z \sin \lambda$$

$$e^{i\lambda \hat{\sigma}_z} = \cos \lambda \hat{I} + i \hat{\sigma}_z \sin \lambda$$

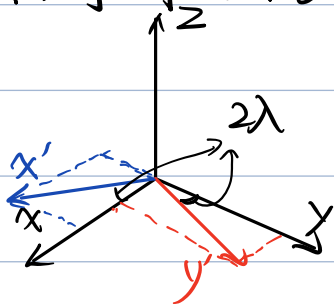
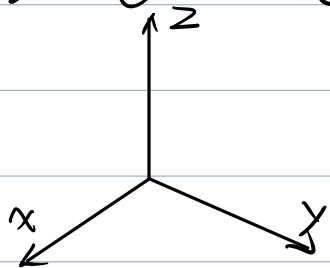
$$\begin{aligned} R_1) e^{i\lambda \hat{\sigma}_z} \hat{\sigma}_x e^{-i\lambda \hat{\sigma}_z} &= (\cos \lambda \hat{I} + i \hat{\sigma}_z \sin \lambda) \hat{\sigma}_x (\cos \lambda \hat{I} - i \hat{\sigma}_z \sin \lambda) \\ &= \cos 2\lambda \hat{\sigma}_x - \sin 2\lambda \hat{\sigma}_y \end{aligned}$$

$$e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_y e^{-i\lambda\hat{\sigma}_z} = (\cos\lambda\hat{I} + i\hat{\sigma}_z \sin\lambda) \hat{\sigma}_y (\cos\lambda\hat{I} - i\hat{\sigma}_z \sin\lambda)$$

$$= \cos 2\lambda \hat{\sigma}_y + \sin 2\lambda \hat{\sigma}_x$$

$$e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_z e^{-i\lambda\hat{\sigma}_z} = \hat{\sigma}_z$$

注: $e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_\alpha e^{-i\lambda\hat{\sigma}_z}$ 相当于将 $\hat{\sigma}_\alpha$ 绕 $\hat{\sigma}_z$ 顺时针转 2λ .



4. 假设某粒子自旋初态为 z 方向自旋的本征态 $|\downarrow\rangle$ 。从 0 时刻到 t 时刻, 体系的 Hamiltonian

为 $\hat{H}_I = A\hbar\hat{\sigma}_x$; 从 t 时刻到 $t + \tau$ 时刻, 体系的 Hamiltonian 为 $\hat{H}_{II} = \frac{1}{2}\hbar\omega(\hat{\sigma}_z + 1)$; 从

$t + \tau$ 时刻到 $2t + \tau$ 时刻, 体系的 Hamiltonian 为 $\hat{H}_I = A\hbar\hat{\sigma}_x$ 。试求在 $2t + \tau$ 时刻测量粒

子处在 $|\downarrow\rangle$ 的几率。

解: 由课上的结论:
$$\begin{cases} |\uparrow\rangle_z = \frac{\sqrt{2}}{2} (|\uparrow\rangle_x + |\downarrow\rangle_x) \\ |\downarrow\rangle_z = \frac{\sqrt{2}}{2} (|\uparrow\rangle_x - |\downarrow\rangle_x) \end{cases}$$

$$\text{则 } e^{-\frac{i\hat{H}_I t}{\hbar}} |\downarrow\rangle_z$$

$$= e^{-iAt\hat{\sigma}_x} \frac{\sqrt{2}}{2} (|\uparrow\rangle_x - |\downarrow\rangle_x)$$

$$= \frac{\sqrt{2}}{2} (e^{-iAt} |\uparrow\rangle_x - e^{iAt} |\downarrow\rangle_x) = |\psi(t)\rangle$$

$$\text{而 } |\uparrow\rangle_x = \frac{\sqrt{2}}{2} (|\uparrow\rangle_z + |\downarrow\rangle_z)$$

$$|\downarrow\rangle_x = \frac{\sqrt{2}}{2} (|\uparrow\rangle_z - |\downarrow\rangle_z)$$

$$\begin{aligned} \text{则 } |\psi(t)\rangle &= e^{-iAt} \frac{1}{\sqrt{2}} (|\uparrow\rangle_z + |\downarrow\rangle_z) - e^{iAt} \frac{1}{\sqrt{2}} (|\uparrow\rangle_z - |\downarrow\rangle_z) \\ &= \frac{1}{\sqrt{2}} (e^{-iAt} - e^{iAt}) |\uparrow\rangle_z + \frac{1}{\sqrt{2}} (e^{-iAt} + e^{iAt}) |\downarrow\rangle_z \end{aligned}$$

$$\text{则 } |\psi(t+\tau)\rangle = e^{\frac{-i\hat{H}_0\tau}{\hbar}} |\psi(t)\rangle$$

$$= e^{-i\frac{\omega}{2}(\hat{\sigma}_z + 1)\tau} |\psi(t)\rangle$$

$$= \frac{1}{\sqrt{2}} (e^{-iAt} - e^{iAt}) e^{-i\omega\tau} |\uparrow\rangle_z + \frac{1}{\sqrt{2}} (e^{-iAt} + e^{iAt}) |\downarrow\rangle_z$$

$$= -i \sin At e^{-i\omega\tau} |\uparrow\rangle_z + \cos At |\downarrow\rangle_z$$

$$= -\frac{\sqrt{2}}{2} i \sin At e^{-i\omega\tau} (|\uparrow\rangle_x + |\downarrow\rangle_x) + \frac{\sqrt{2}}{2} \cos At (|\uparrow\rangle_x - |\downarrow\rangle_x)$$

$$= \frac{\sqrt{2}}{2} (\cos At - i \sin At e^{-i\omega\tau}) |\uparrow\rangle_x - \frac{\sqrt{2}}{2} (i \sin At e^{-i\omega\tau} + \cos At) |\downarrow\rangle_x$$

$$\text{则 } |\psi(2t+\tau)\rangle = e^{\frac{-i\hat{H}_0\tau}{\hbar}} |\psi(t+\tau)\rangle$$

$$= e^{-iAt\hat{\sigma}_x} |\psi(t+\tau)\rangle$$

$$= \frac{\sqrt{2}}{2} (\cos At - i \sin At e^{-i\omega\tau}) e^{-iAt} |\uparrow\rangle_x - \frac{\sqrt{2}}{2} (i \sin At e^{-i\omega\tau} + \cos At) e^{iAt} |\downarrow\rangle_x$$

$$= \frac{1}{2} (\cos At - i \sin At e^{-i\omega\tau}) e^{-iAt} (|\uparrow\rangle_z + |\downarrow\rangle_z)$$

$$- \frac{1}{2} (i \sin At e^{-i\omega\tau} + \cos At) e^{iAt} (|\uparrow\rangle_z - |\downarrow\rangle_z)$$

$$|\downarrow\rangle_z \text{ 前的系数 } C_1 = \frac{1}{2} (\cos At - i \sin At e^{-i\omega\tau}) e^{-iAt}$$

$$+ \frac{1}{2} (\cos At + i \sin At e^{-i\omega\tau}) e^{iAt}$$

$$= \cos^2 At + i \sin At e^{-i\omega\tau} (i \sin At)$$

$$= \cos^2 At - \sin^2 At e^{-i\omega\tau}$$

$$\text{则 几率为 } |C_1|^2 = |\cos^2 At - \sin^2 At e^{-i\omega\tau}|^2$$

$$= [\cos^2 At - \sin^2 At \cos(\omega\tau)]^2 +$$

$$\sin^2 A t \sin^2 \omega t$$

$$= \cos^4 A t - 2 \sin^2 A t \cos^2 A t \cos^2 \omega t + \sin^4 A t$$

$$= 1 - 2 \cos^2 A t \sin^2 A t - 2 \sin^2 A t \cos^2 A t \cos^2 \omega t$$

$$= 1 - 2 \cos^2 A t \sin^2 A t (1 + \cos^2 \omega t)$$

量子力学第九次作业答案

By 鸽子

1.

1. 解: a. 只考虑 $l=1$ 的子空间. m 可能的取值为 ± 1 和 0 .

$$\text{设 } |1, -1\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad |1, 0\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad |1, 1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{由 } \begin{cases} \hat{l}_+ = \hat{l}_x + i\hat{l}_y \\ \hat{l}_- = \hat{l}_x - i\hat{l}_y \end{cases} \quad \hat{l}_\pm |l, m\rangle = \sqrt{(l \mp m)(l \pm m + 1)} \hbar |l, m \pm 1\rangle$$

$$\text{可得 } \hat{l}_y \text{ 的矩阵表示为 } \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\therefore \hat{l}_y^2 \text{ 的矩阵表示为 } \frac{\hbar^2}{\sqrt{2}(-i)} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} = \frac{\hbar^2}{\sqrt{2}i} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$=: \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

b. 设 \hat{l}_y^2 的本征值为 λ

$$\text{令 } |\hat{l}_y^2 - \lambda I| = \begin{vmatrix} \frac{\hbar^2}{2} - \lambda & 0 & -\frac{\hbar^2}{2} \\ 0 & \hbar^2 - \lambda & 0 \\ -\frac{\hbar^2}{2} & 0 & \frac{\hbar^2}{2} - \lambda \end{vmatrix} = (\frac{\hbar^2}{2} - \lambda)(\hbar^2 - \lambda) - (\frac{\hbar^2}{2})(\frac{\hbar^2}{2}) = 0$$

$$\therefore \lambda = \hbar^2 \text{ 或 } 0$$

$$\textcircled{1} \lambda = \hbar^2 \cdot \begin{pmatrix} \frac{\hbar^2}{2} & 0 & -\frac{\hbar^2}{2} \\ 0 & \hbar^2 & 0 \\ -\frac{\hbar^2}{2} & 0 & \frac{\hbar^2}{2} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \hbar^2 \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad \therefore \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \\ -a \end{pmatrix}$$

本征值简并，在该子空间内取两个正交的基。

$$|A_1\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \sqrt{2} \\ -1 \end{pmatrix} \quad |A_2\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -\sqrt{2} \\ -1 \end{pmatrix}$$

$$\textcircled{2} \lambda = 0 \quad \begin{pmatrix} \frac{\hbar^2}{2} & 0 & -\frac{\hbar^2}{2} \\ 0 & \hbar^2 & 0 \\ -\frac{\hbar^2}{2} & 0 & \frac{\hbar^2}{2} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \quad \therefore \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = |A_3\rangle$$

$$|l=1, m=1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \frac{|A_1\rangle + |A_2\rangle + \sqrt{2}|A_3\rangle}{2}$$

\therefore 在该态上测量 \hat{L}_y ，可能的测值为 \hbar^2 或 $-\hbar^2$ 或 0

其中测值为 \hbar^2 的概率为 $P_1 = \left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^2 = \frac{1}{2}$

测值为 $-\hbar^2$ 的概率为 $P_2 = \left(\frac{\sqrt{2}}{2}\right)^2 = \frac{1}{2}$

c. $\langle l=1, m=1 | \hat{L}_y^2 | l=1, m=1 \rangle = \frac{\hbar^2}{2}$

2. Verifizieren

$$a. \{\sigma_x, \sigma_x\} = 2 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_y, \sigma_y\} = 2 \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_z, \sigma_z\} = 2 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{\sigma_x, \sigma_y\} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\{\sigma_x, \sigma_z\} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\{\sigma_y, \sigma_z\} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

b. $\sigma_x \sigma_x = \sigma_y \sigma_y = \sigma_z \sigma_z = I$, $\sigma_i \sigma_j = I$

$$\sigma_x \sigma_y = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = i \sigma_z$$

$$\sigma_y \sigma_z = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = -i \sigma_x$$

$$\sigma_y \sigma_x = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = -i \sigma_z$$

$$\sigma_z \sigma_y = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix} = -i \sigma_x$$

$$\sigma_x \sigma_z = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = -i \sigma_y$$

$$\sigma_z \sigma_x = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = i \sigma_y$$

$\Rightarrow \sigma_i \sigma_j = \delta_{ij} + i \sum_{k \neq i, j} \epsilon_{ijk} \sigma_k$

c. $M = M_0 \sigma_0 + M_1 \sigma_x + M_2 \sigma_y + M_3 \sigma_z = \begin{pmatrix} M_0 + M_3 & M_1 - i M_2 \\ M_1 + i M_2 & M_0 - M_3 \end{pmatrix}$

$$\frac{1}{2} \text{Tr}(M \sigma_0) = \frac{1}{2} \text{Tr} \begin{pmatrix} M_0 + M_3 & M_1 - i M_2 \\ M_1 + i M_2 & M_0 - M_3 \end{pmatrix} = M_0$$

$$\frac{1}{2} \text{Tr}(M \sigma_x) = \frac{1}{2} \text{Tr} \begin{pmatrix} M_1 - i M_2 & M_0 + M_3 \\ M_0 - M_3 & M_1 + i M_2 \end{pmatrix} = M_1$$

$$\frac{1}{2} \text{Tr}(M \sigma_y) = \frac{1}{2} \text{Tr} \begin{pmatrix} M_2 + i M_1 & -i(M_0 + M_3) \\ i(M_0 - M_3) & M_2 - i M_1 \end{pmatrix} = M_2$$

$$\frac{1}{2} \text{Tr}(M \sigma_z) = \frac{1}{2} \text{Tr} \begin{pmatrix} M_0 + M_3 & -M_3 + i M_2 \\ M_1 + i M_2 & M_3 - M_0 \end{pmatrix} = M_3$$

3.

3. 解: $e^{-i\lambda\hat{\sigma}_z} = \cos\lambda - i\hat{\sigma}_z \sin\lambda$

$e^{i\lambda\hat{\sigma}_z} = \cos\lambda + i\hat{\sigma}_z \sin\lambda$

$e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_x e^{-i\lambda\hat{\sigma}_z} = (\cos\lambda + i\hat{\sigma}_z \sin\lambda) \hat{\sigma}_x (\cos\lambda - i\hat{\sigma}_z \sin\lambda)$
 $= \cos 2\lambda \hat{\sigma}_x - \sin 2\lambda \hat{\sigma}_y$

$e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_y e^{-i\lambda\hat{\sigma}_z} = (\cos\lambda + i\hat{\sigma}_z \sin\lambda) \hat{\sigma}_y (\cos\lambda - i\hat{\sigma}_z \sin\lambda)$
 $= \cos 2\lambda \hat{\sigma}_y + \sin 2\lambda \hat{\sigma}_x$

$e^{i\lambda\hat{\sigma}_z} \hat{\sigma}_z e^{-i\lambda\hat{\sigma}_z} = \hat{\sigma}_z$

4.

解: 用同位比算符 $\hat{U} = e^{-i\frac{\hat{A}}{\hbar}t}$
 $\hat{U} = e^{i\frac{\hat{A}}{\hbar}t} = e^{-iA\hat{\sigma}_z t} = \begin{pmatrix} \frac{e^{-iAt} + e^{iAt}}{2} & \frac{e^{-iAt} - e^{iAt}}{2} \\ \frac{e^{-iAt} - e^{iAt}}{2} & \frac{e^{-iAt} + e^{iAt}}{2} \end{pmatrix}$

证: 用和用 $e^A = \sum_n e^{An} |\psi_n\rangle \langle \psi_n|$

$\hat{U}_I = e^{-i\frac{\hat{A}}{\hbar}t} = e^{-i\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \omega t} = \begin{pmatrix} e^{-i\omega t} & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$
 $= \begin{pmatrix} e^{-i\omega t} & 0 \\ 0 & 1 \end{pmatrix}$

$\hat{U}_II = e^{-i\frac{\hat{A}}{\hbar}t} = \hat{U}_I \quad \mathbb{R} |\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad |\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

\therefore 证 $|\psi(t+\tau)\rangle = \hat{U}_II \hat{U}_I \hat{U}_I |\psi(0)\rangle$

$= \begin{pmatrix} \frac{e^{-iAt} + e^{iAt}}{2} & \frac{e^{-iAt} - e^{iAt}}{2} \\ \frac{e^{-iAt} - e^{iAt}}{2} & \frac{e^{-iAt} + e^{iAt}}{2} \end{pmatrix} \begin{pmatrix} e^{-i\omega t} & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{e^{-iAt} + e^{iAt}}{2} & \frac{e^{-iAt} - e^{iAt}}{2} \\ \frac{e^{-iAt} - e^{iAt}}{2} & \frac{e^{-iAt} + e^{iAt}}{2} \end{pmatrix}$

$= \begin{pmatrix} \cos At & -i\sin At \\ -i\sin At & \cos At \end{pmatrix} \begin{pmatrix} -i\sin At \cdot e^{-i\omega t} \\ \cos At \end{pmatrix}$

$= \begin{pmatrix} -i\sin At \cos At (1 + e^{-i\omega t}) \\ \cos^2 At - \sin^2 At e^{-i\omega t} \end{pmatrix}$

$= -i\sin At \cos At (1 + e^{-i\omega t}) |\uparrow\rangle + (\cos^2 At - \sin^2 At e^{-i\omega t}) |\downarrow\rangle$

$\therefore 2t + \tau$ 时刻测量粒子处在 $|b\rangle$ 的概率为

$$P = |\cos^2 At - \sin^2 At e^{-i\omega\tau}|^2 = \cos^4 At - 2\cos^2 At \sin^2 At \cos \omega\tau + \sin^4 At$$