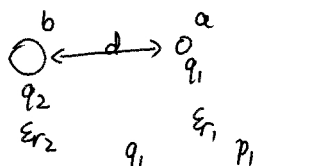


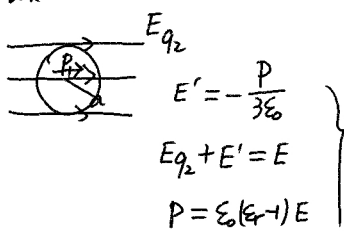
两带电介质球之间的相互作用



电荷分布
 0.1级: $\frac{q_1}{2} + \text{偶极子} + \dots$
 $\frac{q_2}{2} + \text{偶极子} + \dots$

0.5级: $F = \frac{q_1 q_2}{4\pi\epsilon_0} \frac{1}{d^2}$ 斥力为正

0.5级



$E_{q_2} = E + \frac{1}{3\epsilon_0} \epsilon_0(\epsilon_2 - 1)E$

$E = \frac{3}{\epsilon_2 + 2} E_{q_2}$

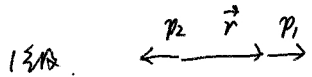
$p_1 = \frac{4}{3}\pi a^3 \epsilon_0 (\epsilon_2 - 1) \frac{3}{\epsilon_2 + 2} \frac{q_2}{4\pi\epsilon_0} \frac{1}{d^2} = \frac{\epsilon_2 - 1}{\epsilon_2 + 2} \frac{q_2 a^3}{d^2}$ 3/10

$F_{q_2 \text{ 对 } p_1} = (p_1 \cdot \nabla) E_{q_2} = \frac{\epsilon_2 - 1}{\epsilon_2 + 2} \frac{q_2 a^3}{d^2} \frac{q_2}{4\pi\epsilon_0} \frac{-1}{d^3} = -\frac{\epsilon_2 - 1}{\epsilon_2 + 2} \frac{q_2^2}{2\pi\epsilon_0} \frac{a^3}{d^5}$

$F_{p_2 \text{ 对 } q_1} = F_{q_1 \text{ 对 } p_2}$
 $= -\frac{\epsilon_2 - 1}{\epsilon_2 + 2} \frac{q_1^2}{2\pi\epsilon_0} \frac{b^3}{d^5}$

$\epsilon_{r1}, \epsilon_{r2} \rightarrow \infty$

$F = -\frac{q_1^2 b^3 + q_2^2 a^3}{2\pi\epsilon_0 d^5}$



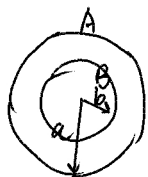
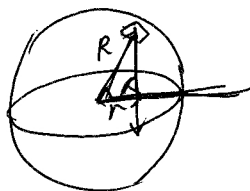
$F_{p_2 \text{ 对 } p_1} = -p_1 p_2 \hat{r} - p_1 p_2 \hat{r} - p_1 p_2 \hat{r}$
 $\frac{3}{4\pi\epsilon_0 d^4} [(\vec{p}_1 \cdot \hat{r}) \vec{p}_2 + (\vec{p}_2 \cdot \hat{r}) \vec{p}_1 + (\vec{p}_1 \cdot \vec{p}_2) \hat{r}$
 $- 5(\vec{p}_1 \cdot \hat{r})(\vec{p}_2 \cdot \hat{r}) \hat{r}]$
 $- 5 p_1 \cdot p_2 \hat{r}$
 $= \frac{3 p_1 p_2 \hat{r}}{2\pi\epsilon_0 d^4} = \dots$

$$F \propto \frac{1}{r^{2+\delta}}$$

Maxwell 验证 $\delta=0$.

$$E = \frac{q}{4\pi\epsilon_0} \frac{1}{r^{2+\delta}} \text{ 仍保守有势}$$

$$\left(V = \frac{q}{4\pi\epsilon_0} \frac{1}{1+\delta} \frac{1}{r^{1+\delta}} \quad V(\infty)=0 \right)$$



$$\frac{1}{1+\delta} \frac{R^2 \sigma}{4\pi\epsilon_0} \int_S \frac{\sin\theta \, d\theta \, d\varphi}{(R^2 + r^2 - 2Rr \sin\theta \cos\varphi)^{\frac{1+\delta}{2}}}$$

$$\int_{-1}^1 du \frac{2\pi}{(R^2 + r^2 - 2Rru)^{\frac{1+\delta}{2}}}$$

① AB 接通加高压 V_0 .

② 拆去导线 假设 $\delta \neq 0$ 则 B 带电.

③ A 接地

④ 求 V_B

$$2\pi \frac{\sigma}{1+\delta} \frac{1}{-2Rr} (R^2 + r^2 - 2Rru)^{\frac{1+\delta}{2}} \Big|_{-1}^1$$

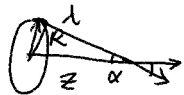
$$(R-r)^{1+\delta} - (R+r)^{1+\delta}$$

$$V(r) = \frac{\sigma R^2}{4\pi\epsilon_0} \frac{1}{1+\delta} \frac{2\pi}{Rr} \left((R+r)^{1+\delta} - (R-r)^{1+\delta} \right)$$



→ 导体电荷分布.

圆环在轴线上的电场

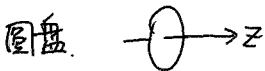


$$\int \frac{\lambda R d\theta \cos \alpha}{4\pi\epsilon_0 R^2 + z^2}$$

$$E = \frac{\lambda 2\pi R}{4\pi\epsilon_0} \frac{z}{(R^2 + z^2)^{3/2}}$$

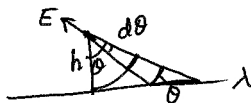
$$\frac{dE}{dz} = k \left(-\frac{3}{2} \frac{z \cdot 2z}{(R^2 + z^2)^{5/2}} + \frac{1}{(R^2 + z^2)^{3/2}} \right)$$

$$= k \frac{R^2 - 2z^2}{(R^2 + z^2)^{5/2}} = 0 \Rightarrow z = \pm \sqrt{2}R$$

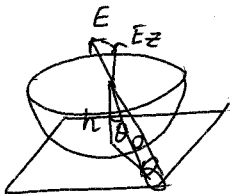


$$\int_0^R \frac{\sigma \cdot 2\pi r dr}{4\pi\epsilon_0} \frac{z}{(r^2 + z^2)^{3/2}} = \frac{\sigma z}{2\epsilon_0} \left(\frac{1}{|z|} - \frac{1}{\sqrt{R^2 + z^2}} \right)$$

等效



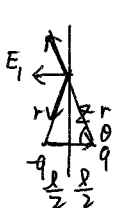
$$E = \frac{\lambda}{4\pi\epsilon_0} \frac{\frac{h}{\cos\theta} d\theta \frac{1}{\cos\theta}}{\left(\frac{h}{\cos\theta}\right)^2} = \frac{\lambda h d\theta}{4\pi\epsilon_0 h^2}$$



$$E_{\text{平面}} = \frac{\sigma}{4\pi\epsilon_0} \frac{\left(\frac{h}{\cos\theta}\right)^2 d\theta \frac{1}{\cos\theta}}{\left(\frac{h}{\cos\theta}\right)^2} = \frac{\sigma d\theta}{4\pi\epsilon_0} \frac{1}{\cos\theta}$$

$$|E_{z\text{平面}}| = |E_{\text{环}}|$$

偶极子的电场

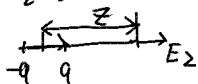


$$E_1 = \frac{q}{4\pi\epsilon_0} \frac{\frac{l}{2} \times 2}{\left(z^2 + \left(\frac{l}{2}\right)^2\right)^{3/2}}$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{1}{z^3} \left(1 + \left(\frac{l}{2z}\right)^2\right)^{-3/2}$$

$$\sim \frac{ql}{4\pi\epsilon_0 z^3} \sim \frac{p}{4\pi\epsilon_0 r^3}$$

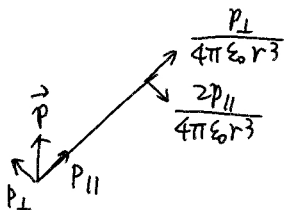
$\frac{l}{2} \quad \frac{l}{2}$



$$E_2 = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{\left(z - \frac{l}{2}\right)^2} - \frac{1}{\left(z + \frac{l}{2}\right)^2} \right)$$

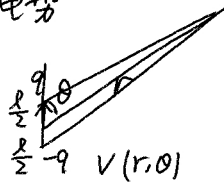
$$\sim \frac{q}{4\pi\epsilon_0} \left[\frac{1}{z^2} \left(1 + 2\frac{l}{2z}\right) - \frac{1}{z^2} \left(1 - 2\frac{l}{2z}\right) \right]$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{2}{z^3} = \frac{2p}{4\pi\epsilon_0 r^3}$$



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{3(\vec{p} \cdot \hat{r})\hat{r} - \vec{p}}{r^3}$$

电势



$$V(r, \theta) = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{\left(r^2 + \left(\frac{l}{2}\right)^2 - rl \cos \theta\right)^{-1/2}} - \frac{1}{\left(r^2 + \left(\frac{l}{2}\right)^2 + rl \cos \theta\right)^{-1/2}} \right]$$

$$\sim \frac{p \cos \theta}{4\pi\epsilon_0 r^2}$$

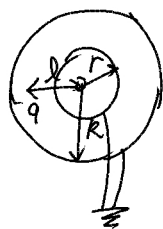
$$Q = \int_V \rho(r') dV'$$

$$\vec{p} = \int_V \rho(r') r' dV'$$

$$\varphi(\vec{R}) = \frac{1}{4\pi\epsilon_0} \left(\frac{Q}{R} - \vec{p} \cdot \nabla \frac{1}{R} + \dots \right)$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{Q}{R} + \frac{\vec{p} \cdot \vec{R}}{R^3} + \dots \right)$$

电场线方程



感应电荷
 Q_1 (内) Q_2 (外)

$$(q + Q_1 + Q_2) \frac{1}{l} + kQ \left(\frac{q}{l} + \frac{Q_1}{r} + \frac{Q_2}{R} \right) = 0$$

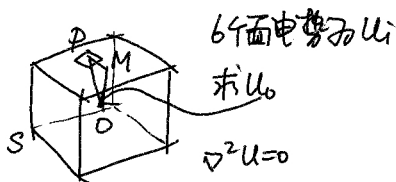
$$\Rightarrow \begin{cases} Q_1 \\ Q_2 \end{cases} \checkmark$$

0点电势为0 (叠加原理)

$$k \left(\frac{Q_1}{r} + \frac{q}{l} + \frac{Q_2}{R} \right) = 0$$

$$\text{又 } Q_1 + Q_2 + q = 0$$

$$\Rightarrow \begin{cases} Q_2 = \frac{l-r}{rR} \frac{q}{l} \\ Q_1 = \frac{l-R}{lR} \frac{q}{l} \end{cases}$$



6个面电势为 U_i

求 U_0

$$\nabla^2 U = 0$$

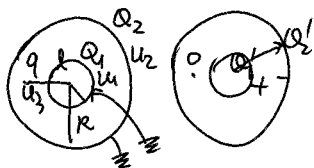
Poisson方程的线性性 $\Rightarrow U_0 = \sum_i k_i U_i$

对称性: $k_i \equiv k$

$U_i \equiv U$ 时唯一性 $U_0 = U \Rightarrow k = \frac{1}{6}$

Green 倒易定理

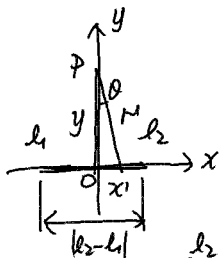
$$\text{综上 } U_0 = \frac{1}{6} \sum_{i=1}^6 U_i$$



$$U' = U_0 + kQ \frac{1}{x}$$

均匀分布

$$q U'_3 + Q_1 U'_1 + Q_2 U'_2 = q' U_3 + Q'_1 U_1 + Q'_2 U_2$$



$$V(h) = \frac{\sigma}{4\pi\epsilon_0} \int_0^R \frac{2\pi r dr}{\sqrt{r^2 + h^2}}$$

$$= \frac{\sigma}{2\epsilon_0} (\sqrt{R^2 + h^2} - |h|)$$

$$V_p = \frac{\lambda}{4\pi\epsilon_0} \int_{l_1}^{l_2} \frac{dx'}{\sqrt{y^2 + (x')^2}}$$

$$= \frac{\lambda}{4\pi\epsilon_0} \ln(x' + \sqrt{(x')^2 + y^2}) \Big|_{x'=l_1}^{l_2}$$

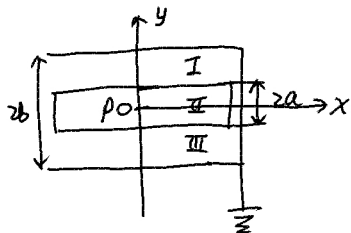
$$= \frac{\lambda}{4\pi\epsilon_0} \ln \left[\frac{l_2 + \sqrt{l_2^2 + y^2}}{l_1 + \sqrt{l_1^2 + y^2}} \right]$$

$$\begin{cases} l_1 = -\frac{l}{2} - x \\ l_2 = \frac{l}{2} - x \end{cases}$$

$$= \frac{\lambda}{4\pi\epsilon_0} \ln \left(\frac{\frac{l}{2} - x + \sqrt{(\frac{l}{2} - x)^2 + y^2}}{-\frac{l}{2} - x + \sqrt{(\frac{l}{2} + x)^2 + y^2}} \right) = \phi_0$$

极散点

等势面：椭圆



$V(\infty)$ $\Gamma_{\Sigma 1}$

$$V(\infty) = V(-\infty)$$

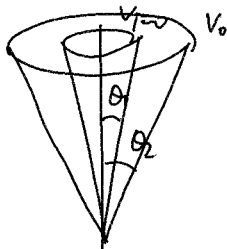
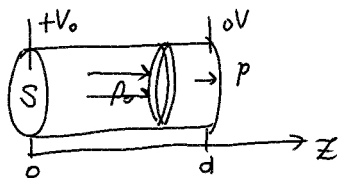
$V(b) = 0$ V 连续 E 连续 无面电荷

$$\frac{d^2V}{dy^2} = \begin{cases} 0 & (a, b) \rightarrow V = k_1 y + C_1 \\ -\frac{\rho}{\epsilon_0} & [-a, a] \rightarrow V = -\frac{\rho}{2\epsilon_0} y^2 + k_2 y + C_2 \end{cases}$$

$$k_2 = 0$$

$$\begin{cases} k_1 b + C_1 = 0 \\ k_1 a + C_1 = -\frac{\rho}{2\epsilon_0} a^2 + C_2 \Rightarrow k_1 C_1 C_2 \\ k_1 = -\frac{\rho}{\epsilon_0} a + C_2 \end{cases}$$

$\Gamma_{\Sigma 2}$ $2E \Delta S = 2a \Delta S \rho / \epsilon_0$
 $E = 2a\rho / \epsilon_0 \quad |y| \in (a, b]$
 $E(y) = \frac{2y\rho}{\epsilon_0} \quad y \in [-a, a]$



$$V(z) \quad E(z)$$

$$\frac{d^2V}{dz^2} = -\frac{\rho_0}{\epsilon_0} \quad V(z) = -\frac{\rho_0}{2\epsilon_0} z^2 + az + b$$

$$\begin{cases} V(0) = V_0 \\ V(d) = 0 \end{cases} \Rightarrow \begin{cases} b = V_0 \\ -\frac{\rho_0}{2\epsilon_0} d^2 + ad + b = 0 \end{cases}$$

$$\begin{cases} b = V_0 \\ a = \frac{1}{d} \left(\frac{\rho_0}{2\epsilon_0} d^2 - b \right) \end{cases}$$

$$E(z) = -\frac{dV}{dz} = \frac{\rho_0}{\epsilon_0} z - \frac{\rho_0 d}{2\epsilon_0} + \frac{b}{d}$$

$$p = \frac{1}{S} \int_0^d S dz \rho_0 E(z)$$

$$= \rho_0 \int_0^d E(z) dz$$

$$= \rho_0 V_0$$

$$\begin{aligned} V &= V(\theta) \\ \nabla^2 V &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0 \end{aligned}$$

$$\frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) = 0$$

$$\sin \theta \frac{\partial V}{\partial \theta} = A$$

$$V = A \ln \left| \tan \frac{\theta}{2} \right| + B = V_0 \frac{\ln \left(\frac{\tan(\theta_2/2)}{\tan(\theta_1/2)} \right)}{\ln \left(\frac{\tan(\theta_2/2)}{\tan(\theta_1/2)} \right)}$$

$$\begin{cases} V(\theta_1) = 0 = A \ln \left(\tan \frac{\theta_1}{2} \right) + B \\ V(\theta_2) = V_0 = A \ln \left(\tan \frac{\theta_2}{2} \right) + B \end{cases}$$

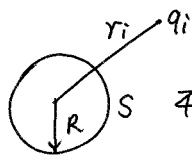
$$\begin{cases} A = V_0 \left(\ln \left(\frac{\tan \frac{\theta_2}{2}}{\tan \frac{\theta_1}{2}} \right) \right)^{-1} \\ B = -V_0 \frac{\ln \left(\tan \frac{\theta_1}{2} \right)}{\ln \left(\frac{\tan \frac{\theta_2}{2}}{\tan \frac{\theta_1}{2}} \right)} \end{cases}$$

电势函数(无电荷时)为调和函数

无极值点 \Rightarrow 带电构形不可能稳定静电平衡

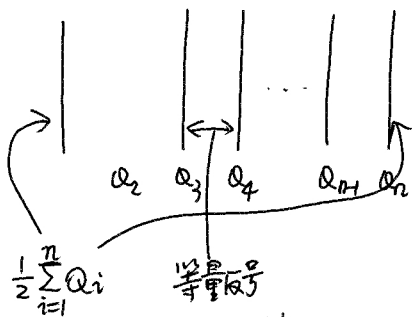
平均值定理

\searrow 推广

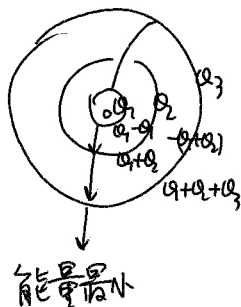
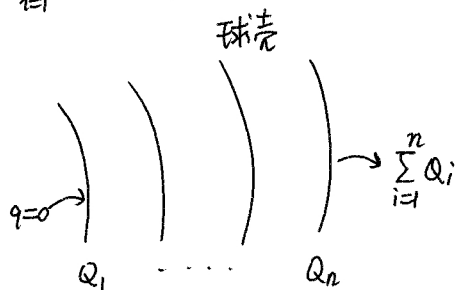


$$\frac{1}{4\pi R^2} \int_S u ds = \overbrace{\frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i}}^{u(0)} + \frac{\sum_i q_i}{4\pi\epsilon_0 R} \frac{1}{R}$$

outside inside



导线连接内外球面



$$W = \frac{1}{2} Q_3 \frac{Q_1 + Q_2 + Q_3}{4\pi\epsilon_0 R_3} + \frac{1}{2} \frac{Q_2}{4\pi\epsilon_0} \left[\frac{Q_1 + Q_2 + Q_3}{R_3} + (Q_1 + Q_2) \left(\frac{1}{R_2} - \frac{1}{R_3} \right) \right]$$

$$+ \frac{1}{2} Q_1 \frac{1}{4\pi\epsilon_0} \left[\frac{Q_1 + Q_2 + Q_3}{R_3} + (Q_1 + Q_2) \left(\frac{1}{R_2} - \frac{1}{R_3} \right) + Q_1 \left(\frac{1}{R_1} - \frac{1}{R_2} \right) \right]$$

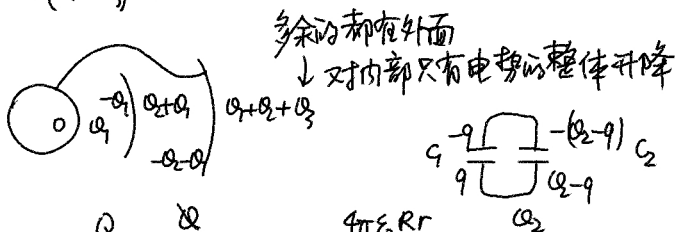
$$= \frac{1}{8\pi\epsilon_0} \frac{(Q_1 + Q_2 + Q_3)^2}{R_3} + \frac{(Q_1 + Q_2)^2}{8\pi\epsilon_0} \left(\frac{1}{R_2} - \frac{1}{R_3} \right) + \frac{Q_1^2}{8\pi\epsilon_0} \left(\frac{1}{R_1} - \frac{1}{R_2} \right) \rightarrow \min$$

$$\frac{1}{8\pi\epsilon_0} \left[\left(\frac{1}{R_1} - \frac{1}{R_3} \right) Q_1^2 + 2 \left(\frac{1}{R_2} - \frac{1}{R_3} \right) Q_2 Q_1 + \left(\frac{1}{R_2} - \frac{1}{R_3} \right) Q_1^2 \right]$$

$$Q_1 = - \frac{\frac{1}{R_2} - \frac{1}{R_3}}{\frac{1}{R_1} - \frac{1}{R_3}} Q_2$$

$$= \frac{R_3 - R_2}{R_3 - R_1} \frac{R_1}{R_2} (Q_2)$$

$\oint (Q_1 + Q_2)$ 总量无关



$$C = \frac{Q}{\Delta U} = \frac{Q}{\frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r} - \frac{1}{R} \right)} = \frac{4\pi\epsilon_0 Rr}{R-r}$$

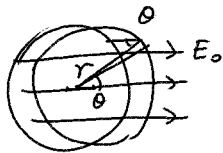
$$W = \frac{1}{2C_1} q^2 + \frac{1}{2C_2} (Q_2 - q)^2$$

$$= \frac{1}{8\pi\epsilon_0} \left[\frac{R_2 - R_1}{R_1 R_2} q^2 + \frac{R_3 - R_2}{R_2 R_3} (Q_2 - q)^2 \right]$$

同理...

$$\begin{cases} \frac{q_1}{C_1} = U_1 = U_2 = \frac{q_2}{C_2} \\ q_1 + q_2 = Q_2 \end{cases}$$

中性导体球在均匀电场 E_0 中
表面感应电荷分布



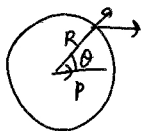
$$F_1 = qE_0 = F_2 = q \cdot \frac{\rho}{3\epsilon_0} r$$

$$\Rightarrow \vec{r} = \frac{3\epsilon_0 \vec{E}_0}{\rho} \longrightarrow \rho = r \cos \theta \rho = 3\epsilon_0 E_0 \cos \theta$$

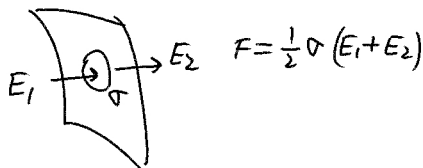
$$\vec{p} = q\vec{r} = 4\pi\epsilon_0 R^3 \vec{E}_0$$

或

$$\sigma = \epsilon_0 E_n = \epsilon_0 \left(\underbrace{\frac{1}{4\pi\epsilon_0 R^3} (3\vec{p} \cdot \hat{r}) \hat{r} - \vec{p}}_2 \cdot \vec{n} + E_0 \cos \theta \right) = 3\epsilon_0 E_0 \cos \theta$$

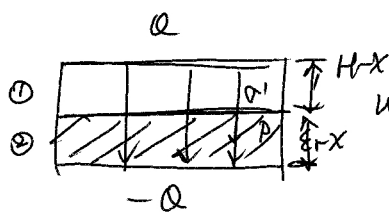
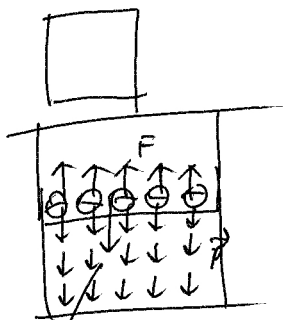


带电平面的受力



适用于带电导体表面等自由电荷面
相反电荷不可。

对导体: $p = w_e = \frac{1}{2} \sigma E_n$ (向外)



$$w_e = \left[\frac{\epsilon_0}{2} \int \vec{E}^2 dV \right] + \left[\int P \cdot \vec{E} dV \right]$$

$$\frac{dW}{dx} = \frac{\sigma^2 S}{2\epsilon_0} \frac{\epsilon_r - 1}{\epsilon_r^2}$$

$$D = \sigma$$

$$E_1 = \frac{1}{\epsilon_0} D = \frac{1}{\epsilon_0} \sigma$$

$$E_2 = \frac{1}{\epsilon_0 \epsilon_r} D = \frac{1}{\epsilon_0 \epsilon_r} \sigma$$

$$w = P = \epsilon_0 (\epsilon_r - 1) E_2 = \frac{\epsilon_r - 1}{\epsilon_r} \sigma$$

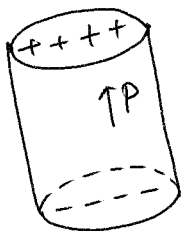
$$F = \frac{\epsilon_r - 1}{\epsilon_r} \sigma \cdot \frac{1}{2} \frac{\sigma}{\epsilon_0} \left(\frac{1}{\epsilon_r} + 1 \right) S$$

$$\frac{\epsilon_0}{2} \left(\frac{\sigma}{\epsilon_0} \right)^2 S (H-x) + \left(\frac{\sigma}{\epsilon_0 \epsilon_r} \right)^2 S x$$

$$= \frac{\sigma^2 S}{2\epsilon_0} \left((H-x) + \frac{1}{\epsilon_r^2} x \right) = W$$

$$\frac{\epsilon_r - 1}{\epsilon_r^2} \frac{\sigma^2 S}{2\epsilon_0} > \frac{\epsilon_r - 1}{\epsilon_r} \frac{\sigma^2 S}{2\epsilon_0}$$

真



$$D \equiv \epsilon_0 E + P.$$

$$P \text{ 未定为 } \epsilon_0(\epsilon - 1)E$$



$$\int_V \frac{\rho(x') \delta(x-x')}{|x-x'|^2} dx'$$

ii

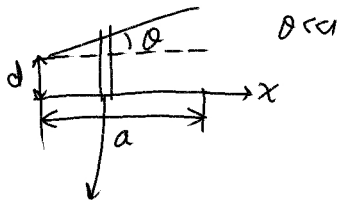
$$\nabla^2 \phi = -\frac{1}{\epsilon} \delta$$

$$\phi = k \frac{1}{r}$$

$$\phi =$$

$$\nabla^2 \phi = -\frac{1}{\epsilon} \rho$$

非平行板电容器



$$dC = \frac{\epsilon_0 b dx}{d + x\theta} \quad \text{并联}$$

$$C = \int dC = \frac{\epsilon_0 b}{\theta} \ln\left(1 + \frac{a\theta}{d}\right)$$

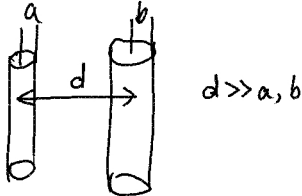
$$\sim \frac{\epsilon_0 b}{\theta} \left(\frac{a\theta}{d} - \frac{1}{2} \frac{a^2\theta^2}{d^2} \right)$$

球形电容器

$$C = 4\pi\epsilon_0 \frac{1}{\frac{1}{R_1} - \frac{1}{R_2}}$$

圆柱形

$$C = 2\pi\epsilon_0 \frac{L}{\ln \frac{b}{a}}$$



单位长度电容值

$$\frac{\lambda}{a} \quad \frac{\lambda}{b} \quad L$$

$$U = \frac{\lambda}{2\pi\epsilon_0} \left(\ln \frac{d-a}{b} + \ln \frac{d-b}{a} \right)$$

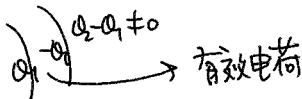
$$= \frac{\lambda L}{2\pi\epsilon_0} \ln \frac{(d-a)(d-b)}{ab}$$

$$C = \frac{2\pi\epsilon_0}{\ln \frac{(d-a)(d-b)}{ab}}$$

$$a = b = r \text{ 且 } d \gg r$$

$$\rightarrow \frac{\pi\epsilon_0}{\ln \frac{d}{r}}$$

带电量不等的两导体

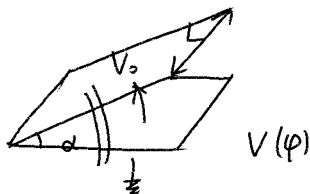


计算电容: 设极板电势 $\phi|_{\partial\Sigma}$

↓
解 Laplace 方程 $\nabla^2\phi=0$

↓
$$\epsilon_0 \int_{\partial\Sigma} \frac{\partial\phi}{\partial n} \cdot dS = Q$$

↓
$$C = \frac{Q}{U_1 - U_2}$$



柱坐标

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2} = 0$$

$$\frac{\partial^2 u}{\partial \phi^2} = 0 \Rightarrow u = k\phi + b$$

$$\begin{cases} u(0) = b = 0 \\ u(\alpha) = k\alpha + b = V_0 \end{cases} \Rightarrow u = \frac{V_0}{\alpha} \phi$$

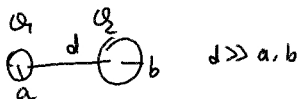
$$\frac{1}{r} \frac{\partial u}{\partial \phi} = \frac{V_0}{\alpha} \frac{1}{r} = E_n = \frac{\sigma}{\epsilon_0}$$

$$Q = \frac{V_0 \epsilon_0 L}{\alpha} \ln \frac{b}{a} \quad C_L = \frac{\epsilon_0}{\alpha} \ln \frac{b}{a}$$

Maxwell 电容矩阵

$$\begin{cases} V_i = p_{ij} Q_j \\ Q_i = C_{ij} V_j \end{cases}$$

$$C_{ij} = \frac{1}{p_{ii} + p_{jj} - 2p_{ji}}$$



$$\begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \frac{1}{4\pi\epsilon_0} \begin{pmatrix} \frac{1}{a} & \frac{1}{d} \\ \frac{1}{d} & \frac{1}{b} \end{pmatrix} \begin{pmatrix} Q_1 \\ Q_2 \end{pmatrix}$$

$$\Rightarrow C_{12} = \frac{4\pi\epsilon_0}{\frac{1}{a} + \frac{1}{b} - \frac{2}{d}}$$

均匀介质板内球内的退极化场

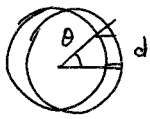
$$\sigma = P \cos \theta$$

$$\sigma = p d \cos \theta$$

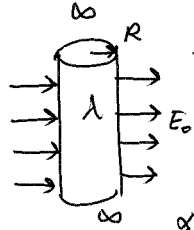
$$E' = -\frac{\rho d}{3\epsilon_0}$$

$$\sigma = 3\epsilon_0 |E'| \cos \theta$$

$$\frac{\epsilon_r - 1}{\epsilon_r + 2} E_0$$



$$\Rightarrow E' = -\frac{P}{3\epsilon_0}$$



均匀介质无限长圆柱

法1

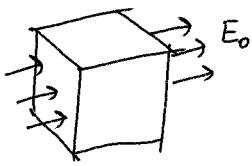
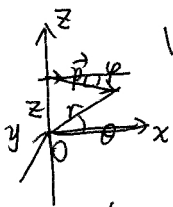
猜解

内部匀强 外部 E_0 + 线偶极

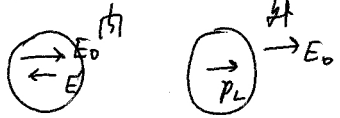
线偶极 (外部)

$$V(r, \theta) = \frac{p_L}{4\pi\epsilon_0} \int_{-\infty}^{+\infty} \frac{r \cos \theta dz}{(r^2 + z^2)^{3/2}}$$

$$= \frac{p_L}{4\pi\epsilon_0} \frac{2r \cos \theta}{r^2} = \frac{p_L \cos \theta}{2\pi\epsilon_0 r}$$

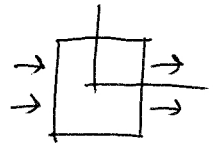


$$\left(\int \frac{dx}{(x^2 + a^2)^{3/2}} = \frac{x}{a^2 \sqrt{x^2 + a^2}} + C \right)$$



(假设)

$$u(r, \theta) = \begin{cases} -E_1 r \cos \theta + C_1 & \text{内} \\ -E_0 r \cos \theta + \frac{p_L \cos \theta}{2\pi\epsilon_0 r} + C_2 & \text{外} \end{cases}$$



$$\begin{cases} u_{in}(R, \theta) = u_{out}(R, \theta) \\ \epsilon_0 \epsilon_r \frac{\partial u_{in}}{\partial r} \Big|_R = \epsilon_0 \frac{\partial u_{out}}{\partial r} \Big|_R \end{cases}$$

$$\begin{cases} -E_1 R \cos \theta \equiv -E_0 R \cos \theta + \frac{P_L \cos \theta}{2\pi \epsilon_0 R} \\ \epsilon_r E_1 \cos \theta \equiv E_0 \cos \theta + \frac{P_L \cos \theta}{2\pi \epsilon_0 R^2} \end{cases} \quad q = C_2$$

假设解.

E_1, P_L 未知

E' 与 P, P 与 P_L 关系未知

为使满足边值关系
解得 E_1, P_L (唯一)

↓
根据 $E' := E_1 - E_0$

$$P := \epsilon_0 (\epsilon_r - 1) E_1$$

解得 E 与 P 的关系
 P 与 P_L

$$\Leftrightarrow \begin{cases} E_1 R = E_0 R - \frac{P_L}{2\pi \epsilon_0 R} \\ \epsilon_r E_1 = E_0 + \frac{P_L}{2\pi \epsilon_0 R^2} \end{cases}$$

$$\Leftrightarrow \begin{cases} P_L = \frac{\epsilon_r - 1}{\epsilon_r + 1} 2\epsilon_0 E_0 \pi R^2 \\ E_1 = \frac{2}{\epsilon_r + 1} E_0 \end{cases} \begin{array}{l} \text{可满足边值关系} \\ \text{由唯一性定理} \\ \text{假设正确} \checkmark \end{array}$$

$$\Rightarrow \begin{cases} P = \epsilon_0 (\epsilon_r - 1) E_1 = 2\epsilon_0 E_0 \frac{\epsilon_r - 1}{\epsilon_r + 1} = P_L / \pi R^2 \\ E' = E_1 - E_0 = -\frac{P}{2\epsilon_0} \end{cases}$$

法2.

认为正负电荷整体偏移了 d (无埋的模型)



$$\begin{aligned} E' &= -\frac{P d}{2\epsilon_0} = -\frac{P}{2\epsilon_0} \quad \text{匀强} \\ P &= \epsilon_0 (\epsilon_r - 1) \left(E_0 - \frac{P}{2\epsilon_0} \right) \Rightarrow P \\ P_L &= P \pi R^2 \end{aligned}$$

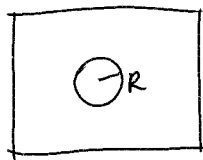
↓
(E' 与 P 的关系)
 $P_L = P \pi R^2$

↓
得解 (唯一性)

$$\frac{\epsilon_r - 1}{\epsilon_r + 2} = \eta \frac{\epsilon_{r1} - 1}{\epsilon_{r1} + 2} + (1 - \eta) \frac{\epsilon_{r2} - 1}{\epsilon_{r2} + 2} \quad \text{why?}$$

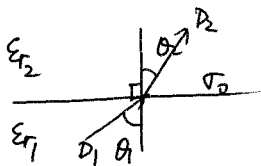
介质界面对 E, D 的折射

无限大均匀介质中 q_f 均匀带电球' (R)



$$q_f \rightarrow \frac{q_f}{\epsilon_r}$$

$$E_f \rightarrow \frac{E_f}{\epsilon_r}$$



$$\begin{cases} \frac{D_2 \sin \theta_2}{\epsilon_2} = \frac{D_1 \sin \theta_1}{\epsilon_1} \\ D_2 \cos \theta_2 = D_1 \cos \theta_1 \end{cases}$$

$$D_2 \cos \theta_2 - D_1 \cos \theta_1 = \sigma_0$$

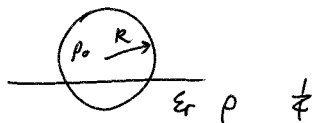
空间充满均匀介质
介质界面为等势面 } $\nabla \times D = 0$

$$\frac{\tan \theta_1}{\tan \theta_2} = \frac{\epsilon_{r1}}{\epsilon_{r2}} \left(1 + \frac{\sigma_0}{\epsilon_0 \epsilon_{r1} E_1 \cos \theta_1} \right)$$

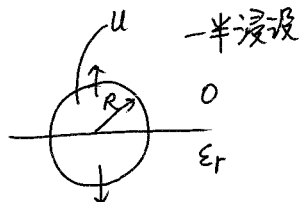
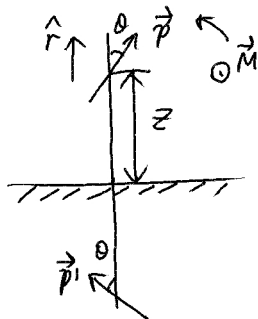
空间中存在多种介质时

界面 { 平行于等势面
垂直于等势面

无限大介质去掉一个球'



$$\rho_0 = \frac{1}{2}\rho$$



E相同

$$E = k \frac{1}{r^2} \quad U_0 = k \frac{1}{R}$$

$$\parallel$$

$$\frac{U_0 R}{r^2}$$

$$\begin{cases} P_L = W_e = \frac{\epsilon_0}{2} E^2 \\ P_T = \frac{1}{2} D \cdot E = \frac{\epsilon_0}{2} \epsilon_r E^2 \end{cases}$$

$$F = \frac{\epsilon_0}{2} \frac{U_0^2 R^2}{R^4} (\epsilon_r - 1) \pi R^2 = \frac{1}{4} \cdot \rho \cdot \frac{4}{3} \pi R^3 g$$

向下

$$\Rightarrow U_0$$

$$W = -p \cdot E \cdot \frac{1}{2}$$

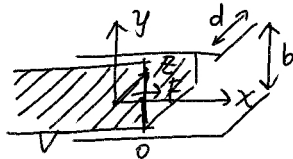
$$= -\frac{1}{8\pi\epsilon_0 (z^2)^3} (3(\vec{p} \cdot \hat{r})(\hat{p} \cdot \hat{r}) - \vec{p} \cdot \vec{p})$$

$$= -\frac{p^2 (\cos^2\theta + 1)}{64\pi\epsilon_0 z^3}$$

$$F = -\frac{dW}{dz} = \frac{3p^2 (\cos^2\theta + 1)}{64\pi\epsilon_0 z^4} (\hat{r})$$

$$M = -\frac{dW}{d\theta} = \frac{p^2}{64\pi\epsilon_0 z^3} \sin 2\theta$$

力矩



$$f_x = \frac{\epsilon_r - 1}{\epsilon_r} \partial_x w$$

$$F_x = \int_V f_x dV = \frac{\epsilon_r - 1}{\epsilon_r} \int_0^b dy \int_0^d dz \underbrace{\int_{-\infty}^0 \partial_x w dx}_{w(0) - w(-\infty)}$$

\downarrow
 介质的力

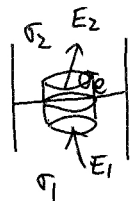
$$= \frac{\epsilon_r - 1}{\epsilon_r} b d \frac{\epsilon_0 \epsilon_r (V/d)^2}{2}$$

电流

$$\vec{j} = \rho \vec{v}$$

$$\vec{j} = \sigma \vec{E} \quad (\text{部分导体})$$

在不同导体分面上



$$\vec{n} \cdot (\vec{E}_2 - \vec{E}_1) = \frac{\sigma_2}{\sigma_1} \frac{j_2}{\sigma_2} - \frac{j_1}{\sigma_1}$$

$$\text{稳恒时 } j_2 = j_1 = \frac{I}{S}$$

$$\Rightarrow \sigma = \frac{I \epsilon_0}{S} \left(\frac{1}{\sigma_2} - \frac{1}{\sigma_1} \right)$$

稳恒电流时

欧姆定律 \Rightarrow 焦耳热最小

利用 $R = \int \frac{\rho dl}{S}$ 时

导体截面 S 应为等势面



$$R = \frac{U}{I} = \frac{\int \vec{E} \cdot d\vec{l}}{\int \vec{j} \cdot d\vec{s}}$$

取 L 为电流线/电场线

$$S \text{ 为等势面} \Rightarrow \vec{j} \parallel d\vec{s}$$

$$\frac{\int \rho j dl}{\int j ds} = \int \frac{\rho j}{j ds} dl$$

同截面上各处 j 相同时

$$\int \frac{\rho j}{j ds} dl = \int \frac{\rho dl}{S}$$

看成电阻串联



$$\textcircled{1} E = \frac{Q}{4\pi\epsilon r^2} \quad U_0 = \frac{Q}{4\pi\epsilon} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$Q = 4\pi\epsilon U_0 \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$E = \frac{U_0}{r^2} \frac{b-a}{ab}$$

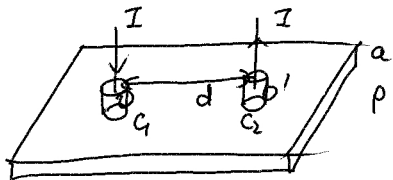
$$j = \sigma E$$

$$I = \sigma \frac{U_0}{\rho^2} \frac{b-a}{ab} 4\pi a^2 = 4\pi\sigma U_0 \frac{b-a}{ab}$$

$$\textcircled{2} R = \frac{U_0}{I} = \frac{ab}{4\pi\sigma(b-a)} = \rho \epsilon \frac{1}{C}$$

$$RC = \rho \epsilon$$

$$\textcircled{3} R = \int \frac{\rho dl}{S} = \rho \int \frac{dr}{4\pi r^2} = \frac{\rho}{4\pi} \left(\frac{1}{a} - \frac{1}{b} \right)$$



$$2\pi r a \cdot j_1 = I$$

$$j_1 = \sigma E_1$$

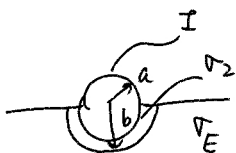
$$E_1 = \frac{I}{2\pi\sigma a r_1} \quad E_2 = \frac{I}{2\pi\sigma a r_2}$$

$$j = j_1 + j_2 \Rightarrow E = E_1 + E_2$$

$$U_{12} = \frac{I}{2\pi\sigma a} \int_a^{d-c_2} \left(\frac{1}{r_1} + \frac{1}{d-r_1} \right) dr$$

$$= \frac{I}{2\pi\sigma a} \ln \left(\frac{d-c_2}{a} \cdot \frac{d}{c_2} \right)$$

R



$$\vec{j} = \frac{I \hat{r}}{2\pi r^2} \quad \vec{E} = \frac{1}{\sigma} \vec{j}$$

$$U = \int_{+\infty}^a E dr = \frac{I}{2\pi} \left[\frac{1}{\sigma_2} \left(\frac{1}{a} - \frac{1}{b} \right) + \frac{1}{\sigma_1} \frac{1}{b} \right]$$

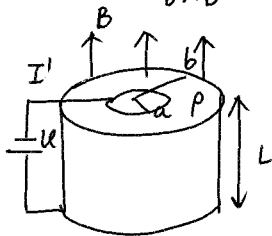
R

含源电路

$$\vec{j} = \sigma (\vec{E} + \vec{K})$$

$$\downarrow \sigma \vec{v}$$

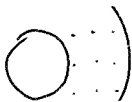
$$\vec{v} \times \vec{B}$$



(r, θ)

$$\vec{E}(r, \theta) = \frac{U_0}{\ln \frac{b}{a}} \frac{\hat{r}}{r}$$

$L \gg b > a$



$$\vec{v} = v_r \hat{r} + v_\theta \hat{\theta}$$

$$\vec{K} = \vec{v} \times \vec{B} = v_\theta B \hat{r} - v_r B \hat{\theta}$$

$$\vec{j} = ne\vec{v}$$

$$\vec{j} = \sigma (\vec{E} + \vec{K})$$

$$\begin{cases} nev_r = \sigma \left(\frac{U_0}{\ln \frac{b}{a}} \frac{1}{r} + v_\theta B \right) \\ nev_\theta = \sigma (-v_r B) \end{cases}$$

$$\left(ne + \frac{\sigma^2 B^2}{ne} \right) v_r = \frac{\sigma}{r} \frac{U_0}{\ln \frac{b}{a}}$$

$$j_r = nev_r = \frac{\sigma}{r} \frac{U_0}{\ln \frac{b}{a}} \frac{1}{1 + \frac{\sigma^2 B^2}{n^2 e^2}}$$

$$I' = j_r(a) 2\pi a L$$

$$= \frac{2\pi \sigma L U_0}{\ln \frac{b}{a} \left(1 + \frac{\sigma^2 B^2}{n^2 e^2} \right)}$$

$$j_\theta = -\frac{\sigma B}{ne} j_r \propto \frac{1}{r}$$

$$\text{环向电流 } I'' = \int_a^b j_\theta(r) L dr$$

能量损耗

$$P = (j_r^2 + j_\theta^2) P$$

$$P \neq (I')^2 r$$

二维电子气体均匀磁场中的运动

散射力 $\vec{f} = -m\vec{v}/\tau$

$$\begin{cases} m\ddot{x} = -eEx - ev_y B - m\frac{v_x}{\tau} \\ m\ddot{y} = -eEy + ev_x B - m\frac{v_y}{\tau} \end{cases}$$

$$\begin{cases} j_x = -env_x \\ j_y = -env_y \end{cases}$$

稳态:

$$\begin{cases} 0 = -eEx - eBv_y - \frac{m}{\tau}v_x \\ 0 = -eEy + eBv_x - \frac{m}{\tau}v_y \end{cases}$$

$$\begin{pmatrix} \frac{m}{\tau} & eB \\ eB & -\frac{m}{\tau} \end{pmatrix} \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} -eEx \\ eEy \end{pmatrix}$$

$$\begin{pmatrix} v_x \\ v_y \end{pmatrix} = \frac{1}{\left(\frac{m}{\tau}\right)^2 + (eB)^2} \begin{pmatrix} \frac{m}{\tau} & eB \\ eB & -\frac{m}{\tau} \end{pmatrix} \begin{pmatrix} -eEx \\ eEy \end{pmatrix} \quad \begin{cases} \sigma_0 = \frac{ne^2\tau}{m} \\ \omega_c = \frac{eB}{m} \end{cases}$$

$$\begin{pmatrix} \sigma_{xx} & \sigma_{xy} \\ \sigma_{yx} & \sigma_{yy} \end{pmatrix} = \frac{-ne^2}{\left(\frac{m}{\tau}\right)^2 + (eB)^2} \begin{pmatrix} -\frac{m}{\tau} & eB \\ -eB & -\frac{m}{\tau} \end{pmatrix} = \frac{\sigma_0}{H(\omega_c\tau)^2} \begin{pmatrix} 1 & -\omega_c\tau \\ \omega_c\tau & 1 \end{pmatrix}$$

① 已知 σ

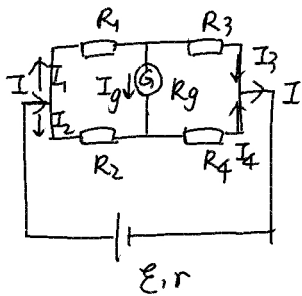
用 $\vec{j} = \sigma(\vec{E} + \vec{v} \times \vec{B})$ 列方程
 $\parallel \vec{j}$
 $ne\vec{v}$ \rightarrow 已是稳态

如 $ne\vec{v} = \sigma(\vec{E} + \vec{v} \times \vec{B}) \Rightarrow \vec{v} \Rightarrow \vec{j}$

② 未知 σ

列运动方程

稳态令加速度为 0 $\Rightarrow \vec{v} = \vec{j}$
 由 \vec{j} 与 \vec{E} 关系得 σ



$$\begin{pmatrix} 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 0 & 1 & -1 \\ 0 & r & 0 & -R_3 & R_4 & R_g \\ 0 & 0 & R_2 & -R_1 & 0 & -R_g - R_1 \\ 0 & -r & -rR_2 & 0 & R_4 & 0 \end{pmatrix} \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} \xrightarrow{R_2}$$

$$I = I_1 + I_2$$

$$I_1 = I_g + I_3$$

$$I_4 = I_g + I_2$$

$$-I_1 R_1 - I_g R_g + I_2 R_2 = 0$$

$$+I_g R_g - I_3 R_3 + I_4 R_4 = 0$$

$$-I_2 R_2 - I_4 R_4 - I r + \varepsilon = 0$$

$$0 \quad 0 \quad 0 \quad \begin{matrix} -R_1 & R_2 & -R_2 R_g - R_1 \end{matrix}$$

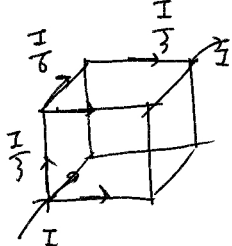
$$0 \quad 0 \quad -rR_2 \quad -rR_4 \quad -r$$

$$0 \quad 0 \quad 0 \quad \begin{matrix} -r & -R_4 - r & -R_2 & R_4 \end{matrix}$$

$$I_g = \frac{\Delta g}{\Delta} \rightarrow \begin{vmatrix} -R_3 & R_4 & 0 \\ -R_1 & R_2 & 0 \\ -r & -rR_2 R_4 & \varepsilon \end{vmatrix}$$

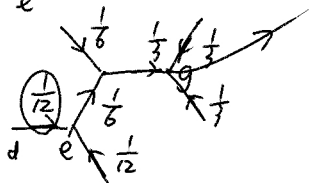
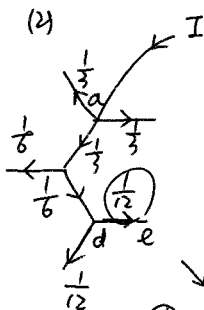
$$\begin{matrix} R_1 \\ r \end{matrix} \begin{pmatrix} 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 0 & 1 & -1 \\ 0 & -R_1 & R_2 & 0 & 0 & -R_g \\ 0 & 0 & 0 & -R_3 & R_4 & R_g \\ -r & 0 & -rR_2 & 0 & -R_4 & 0 \end{pmatrix} \begin{matrix} I \\ I_1 \\ I_2 \\ I_3 \\ I_4 \\ I_g \end{matrix} \begin{matrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \varepsilon \end{matrix}$$

I_g
 \updownarrow
 $R_2 R_3 = R_1 R_4$

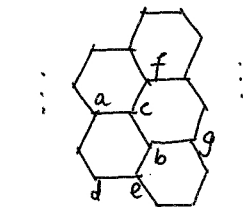
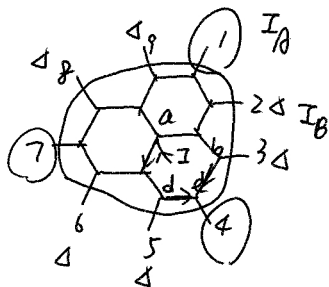


$$U = \left(\frac{I}{3} + \frac{I}{6} + \frac{I}{3}\right) R = \frac{5}{6} IR$$

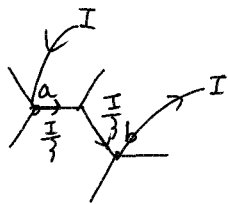
$$R' = \frac{5}{6} R$$



$$I_{de} = \frac{1}{6} I$$



(1)
Rab



$$U = \frac{I}{3} 2r \quad R_{ab} = \frac{2}{3} r$$

$$\text{对 a} \begin{cases} 3I_A + 6I_B = I \\ I'_{de} = I'_{be} = \frac{1}{2} I_A \end{cases}$$

$$\text{对 g: } I''_{de} = I_B$$

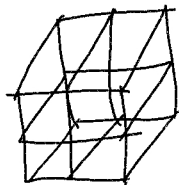
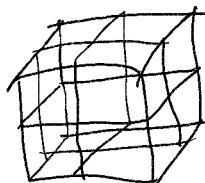
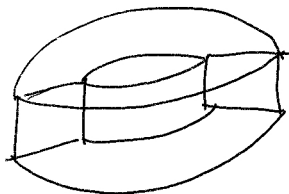
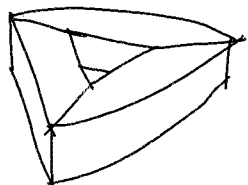
$$I_{de} = I'_{de} + I''_{de} = \frac{1}{2} I_A + I_B = \frac{1}{6} I$$

对称电阻网络

电流叠加 输入与输出电流叠加

对称分析 等势点/线的拆合

无穷电阻网络



$$V - E + F$$

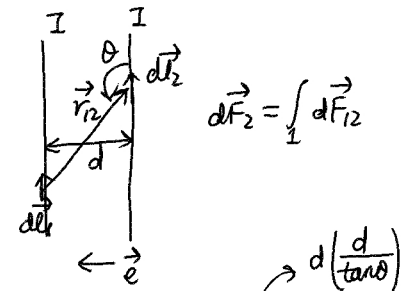
$$8 - 16 + 8 = 0$$

$$\vec{dF}_{12} = \frac{\mu_0}{4\pi} \frac{I_1 I_2 d\vec{l}_2 \times (\vec{dl}_1 \times \hat{r}_{12})}{r_{12}^2}$$

$$d\vec{B}_{12} = \frac{\mu_0}{4\pi} \frac{I_1 d\vec{l}_1 \times \hat{r}_{12}}{r_{12}^2}$$

$$\vec{dF}_{12} = I_2 d\vec{l}_2 \times d\vec{B}_{12}$$

$$\vec{dF}_2 = \int \vec{dF}_{12}$$

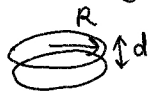


$$dF_{12} = \frac{\mu_0}{4\pi} I^2 dl_2 \frac{dl_1 \sin\theta}{(d/\sin\theta)^2} \vec{e}$$

$$= \frac{\mu_0}{4\pi} I^2 \frac{\sin^3\theta}{d^2} d \frac{1}{\tan^2\theta} \frac{1}{\cos^2\theta} d\theta dl_2$$

$$= \frac{\mu_0 I^2}{4\pi d} \sin\theta d\theta dl_2 \quad (0, \pi)$$

$$dF_2 = \frac{\mu_0 I^2}{2\pi d} dl_2$$



$d \ll R$

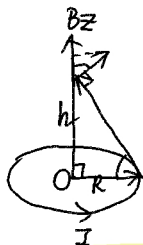
$$F \approx \frac{\mu_0 I^2}{2\pi d} 2\pi R = \frac{\mu_0 I^2 R}{d}$$

$$\vec{F}_{12} = -\vec{F}_{21}$$

$$= \frac{\mu_0}{4\pi} \oint \oint \frac{I_1 I_2 d\vec{l}_2 \times (d\vec{l}_1 \times \hat{r}_{12})}{r_{12}^2}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi r}$$

$$B = \frac{\mu_0 I}{4\pi d} (\cos\theta_1 - \cos\theta_2)$$

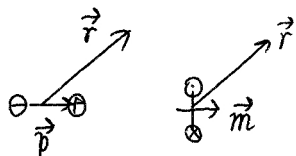


$$B_z = \frac{\mu_0 I}{2} \frac{R^2}{(h^2 + R^2)^{3/2}}$$

$h \gg R$

$$B_z \approx \frac{\mu_0 I}{2} \frac{R^2}{h^3}$$

$$= \frac{\mu_0}{2\pi} \frac{I^2 R^2}{h^3} I \pi R^2$$

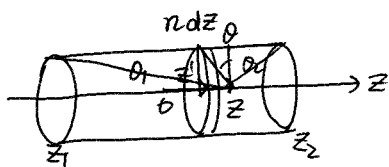


$$\vec{E} = \frac{1}{4\pi\epsilon_0 r^3} (3(\vec{p} \cdot \hat{r})\hat{r} - \vec{p})$$

$$\vec{B} = \frac{\mu_0}{4\pi r^3} (3(\vec{m} \cdot \hat{r})\hat{r} - \vec{m})$$

$$\vec{m} = I\vec{S}$$

$$= I \left(\frac{1}{2} \oint_L \vec{r} \times d\vec{r} \right)$$



$$\int_{z_1}^{z_2} \frac{\mu_0 I R^2}{2(R^2 + (z-z_1)^2)^{3/2}} ndz = B(z)$$

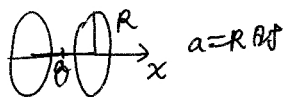
$$z' - z = R \tan \theta$$

$$\frac{\mu_0 I n}{2} (\sin \theta_2 - \sin \theta_1) = B_p$$

$$\textcircled{1} \theta_1 \rightarrow -\frac{\pi}{2} \quad \theta_2 \rightarrow \frac{\pi}{2} \quad B_p \rightarrow \mu_0 n I$$

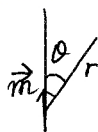
$$\textcircled{2} \theta_1 = 0 \quad \theta_2 \rightarrow \frac{\pi}{2} \quad B_p \rightarrow \frac{1}{2} \mu_0 n I$$

Helmholtz 线圈



$$B'(x) \Big|_{x=0} = B''(x) \Big|_{x=0} = 0$$

$$\frac{\mu_0 m}{4\pi r^3} (2 \cos \theta \vec{e}_r + \sin \theta \vec{e}_\theta)$$



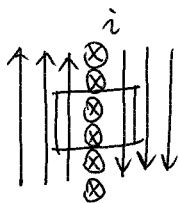
$$\vec{B} = \frac{\mu_0}{4\pi} \oint_L \frac{I d\vec{l} \times \hat{r}}{r^2} \Rightarrow \nabla \cdot \vec{B} = 0$$

电流产生的磁场无源

$$\vec{B} = \frac{\mu_0}{4\pi} \int_{R^3} \frac{\vec{j} \times \hat{r}}{r^2} dV$$

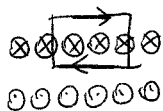
$$\Downarrow$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{j}$$



$$\mu_0 n i l = 2B \Delta l$$

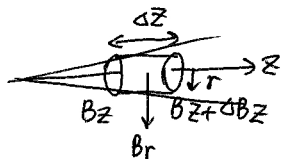
$$B = \frac{1}{2} \mu_0 i$$



理想螺线管

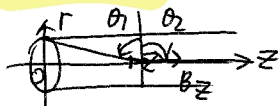
$$B = \mu_0 n I$$

轴对称磁场 B_z B_r



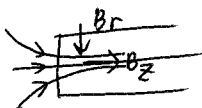
$$B_r 2\pi r \Delta z + \Delta B_z \pi r^2 = 0$$

$$B_r = -\frac{r}{2} \frac{dB_z}{dz} \quad r \text{ 很小}$$



$$B_z = \frac{\mu_0 n I}{2} \left(1 + \frac{z}{\sqrt{z^2 + R^2}} \right)$$

$$B_r(z) = -\frac{\mu_0 n I}{2} \frac{R^2}{(z^2 + R^2)^{3/2}}$$



$$B 2\pi r = \mu_0 N I$$

$$B = \frac{\mu_0 N I}{2\pi r}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{L'} \frac{d\vec{l}' \times \vec{e}_r}{R^2}$$

$$= \frac{\mu_0 I}{4\pi} \oint_{L'} \nabla \times \left(\frac{d\vec{l}'}{R} \right)$$

$$= \nabla \times \vec{A}$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \oint_{L'} \frac{d\vec{l}'}{R}$$

$$\nabla \cdot \vec{A} = 0$$

$$\nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$$

||
 $\nabla \times \vec{B} = \mu_0 \vec{j}$

$$\nabla^2 \vec{A} = -\mu_0 \vec{j}$$

$$(\nabla^2 A_i = -\mu_0 j_i)$$

eg. 均匀 $\vec{B} = B_0 \vec{e}_z$

$$\nabla \times \vec{A} = \vec{B}$$

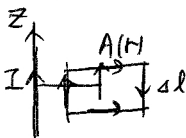
$$\begin{cases} \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} = 0 \\ \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} = 0 \\ \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} = B_0 \end{cases}$$

有多解

$$\vec{A} = \begin{cases} -B_0 y \vec{e}_x \\ B_0 x \vec{e}_y \\ \frac{1}{2} B_0 \times \vec{r} \end{cases}$$

eg. 无限长直导线

取 \vec{A} 平行于导线



$$(A(r_0) - A(r)) \Delta l = \frac{\mu_0 I \Delta l}{2\pi} \int_{r_0}^r \frac{dr}{r}$$

$$\vec{A}(r) = \underbrace{\vec{A}(r_0)}_{\text{取为0}} - \frac{\mu_0 I}{2\pi} \ln \frac{r}{r_0} \vec{e}_z$$

取为0
参考点

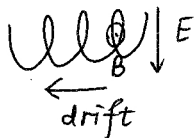
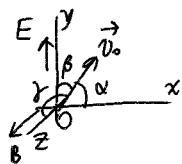
$$U(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{r}}{r^3}$$

eg. 磁矩

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi r^3} (\vec{m} \times \vec{r})$$

带电粒子在磁场中的运动

在任意场中的漂移速度



$$\vec{v}_F = \frac{\vec{E} \times \vec{B}}{B^2}$$

$$\begin{cases} \vec{E} = (0, E, 0) \\ \vec{B} = (0, 0, B) \end{cases}$$



$$\vec{v}_F = \frac{\vec{E} \times \vec{B}}{qB^2}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$EB \sin \theta$

磁场不均匀引起的漂移

$$\begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = q \begin{pmatrix} v_y B \\ E - v_x B \\ 0 \end{pmatrix}$$

$$B_r = -\frac{r}{2} \frac{dB}{dz}$$

$$F = q \vec{v} \times \vec{B}_r = -\mu \nabla B$$



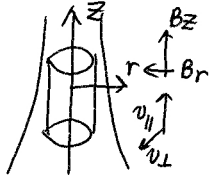
$$\begin{aligned} v_F &= \frac{q(v_{\perp}) \left(\frac{1}{2} \frac{m v_{\perp}}{qB} \frac{dB}{dz} \right) \times B}{qB^2} \\ &= \mu \frac{B \times \nabla B}{qB^2} \end{aligned}$$

$$\begin{cases} \dot{v}_x = \frac{qB}{m} v_y \\ \dot{v}_y = \frac{qE}{m} - \frac{qB}{m} v_x \end{cases} \quad \omega = \frac{qB}{m}$$

$$\ddot{v}_y = -\omega^2 v_y$$

$$\begin{cases} v_y = v_{\perp} \cos(\omega t + \phi) \\ v_x = \frac{E}{B} + v_{\perp} \sin(\omega t + \phi) \\ v_z = v_{\parallel} = v_0 \cos \gamma \end{cases} \rightarrow \text{漂移}$$

轴对称



时空缓变磁场中运动不变量

$$\textcircled{1} \mu = \frac{\frac{1}{2} m v_{\perp}^2}{B}$$

$$\textcircled{2} \phi = B \pi R^2 = 2\pi \frac{m}{q^2} \mu$$

$$B_r = -\frac{r}{2} \frac{dB_z}{dz}$$

$$\mu = \frac{1}{2} \frac{m v_{\perp}^2}{B}$$

$$\frac{d\mu}{dt} = \frac{m}{2} \left(\frac{2v_{\perp}}{B} \frac{dv_{\perp}}{dt} - \frac{v_{\perp}^2}{B^2} \frac{dB}{dt} \right)$$

$$m \frac{dv_{\perp}}{dt} = -q v_{\parallel} B_r \quad \frac{m v_{\perp}^2}{r} = q v_{\perp} B_z$$

$$\frac{dB}{dt} \approx \frac{dB_z}{dt} = \frac{dB_z}{dz} v_{\parallel}$$

$$\frac{m}{2} \left(\frac{2v_{\perp}}{B} - \frac{q B_r}{m} \right) v_{\parallel} - \frac{v_{\perp}^2}{B^2} \frac{dB_z}{dz} v_{\parallel} \approx 0$$

$$\frac{r}{2} \frac{dB_z}{dz}$$

$$B \approx B_z$$

$$\frac{m v_{\perp}}{q B_z}$$

Hall 效应

磁场对电流的作用

- 体电流 \vec{j} 用该点的场
- 面电流 \vec{i} 用两侧平均场
- 线电流 $I\vec{dl}$ x 发散

对载流线圈

均匀 B: $\vec{F} = \vec{0}$ $\vec{M} = \vec{\mu} \times \vec{B}$

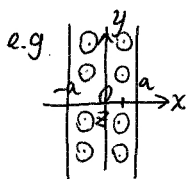
非均匀 B: $\vec{F} = \nabla(\vec{\mu} \cdot \vec{B})$ $\vec{M} = \vec{\mu} \times \vec{B} + \vec{r} \times \vec{F}$

(外场)

$$= B \times (\nabla \times \mu) + \mu \times (\nabla \times B) + (B \cdot \nabla) \mu + (\mu \cdot \nabla) B$$

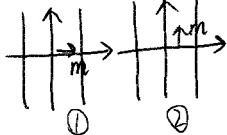
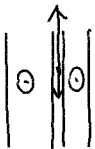
若 μ 不变 μ 处 $\nabla \times B = 0$

$(\mu \cdot \nabla) B$



$$\vec{j}(x) = \begin{cases} j_0 \vec{e}_z & |x| \leq a \\ 0 & |x| > a \end{cases}$$

$$\vec{B}(x) = \begin{cases} \frac{\mu_0}{2} (j_0(x+a) - j_0(a-x)) \vec{e}_y \\ \quad \quad \quad \mu_0 j_0 x \vec{e}_y & |x| \leq a \\ \mu_0 j_0 a \vec{e}_y & x > a \\ -\mu_0 j_0 a \vec{e}_y & x < -a \end{cases}$$



$$\vec{F}_1 = \nabla(\vec{m} \cdot \vec{B}) = 0$$

$$\vec{F}_2 = m \mu_0 j_0 \vec{e}_x$$

不能用 $(\mu \cdot \nabla) B$
因为 μ 处 $\nabla \times B \neq 0$

磁化电流的磁化

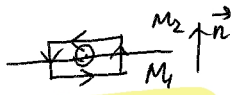
$$\vec{j} = \nabla \times \vec{M}$$

$$\iint_{\text{界面上}} \vec{j} \cdot d\vec{S} = \oint \vec{M} \cdot d\vec{l}$$

界面上
↓

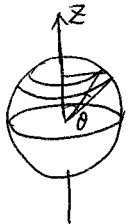
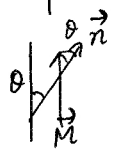
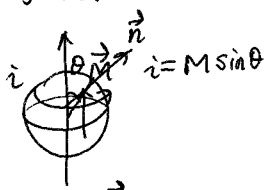
$$\begin{cases} B = \mu_0 H + \mu_0 M \\ D = \epsilon_0 E + P \end{cases}$$

$$\begin{cases} H' = -\frac{1}{3}M & B' = \frac{2}{3}\mu_0 M \\ E' = -\frac{1}{3}\frac{P}{\epsilon_0} & D' = \frac{2}{3}P \end{cases}$$



$$\vec{i} = \vec{n} \times (\vec{M}_2 - \vec{M}_1)$$

e.g. 均匀磁化球磁化电流在轴上产生的



$$R d\theta (M \sin \theta) \frac{\mu_0}{2} \frac{R^2 \sin^2 \theta}{(R^2 \sin^2 \theta + (z - R \cos \theta)^2)^{3/2}}$$

$$\frac{R^3 M \mu_0}{2} \int_0^\pi \frac{\sin^3 \theta d\theta}{(R^2 - 2zR \cos \theta + z^2)^{3/2}}$$

$$= \begin{cases} \frac{\mu_0}{4\pi} \frac{2\mu}{|z|^3} & \text{球外} \\ \frac{2\mu_0 M}{3} & \text{球内} \end{cases} \quad \mu = \frac{4}{3} \pi R^3 M$$

磁化规律

$$M = \chi_m H \quad \text{弱磁性, 线性各向同性} \\ \text{无损耗}$$

$$B = \mu_0 \mu_r H \\ = \mu_0 H + \mu_0 \underbrace{(\mu_r - 1)}_M H \\ \chi_m$$
$$\left(\begin{array}{l} P = \epsilon_0 \chi_e E \\ D = \epsilon_0 \epsilon E \quad P \\ = \epsilon_0 E + \epsilon_0 \underbrace{(\epsilon - 1)}_{\chi_e} E \end{array} \right)$$

顺磁性 $\mu_r > 1$ $\chi_m > 0$ M 与 H 同向

Curie's Law

$$\chi_m \propto \frac{1}{T} \quad (\text{气体})$$

抗磁性 $\mu_r < 1$ $\chi_m < 0$ M 与 H 反向

特殊磁性材料

超导材料

$$\vec{j}_s = n e^* e^* \vec{v}$$

$$m^* \frac{d\vec{v}}{dt} = e^* \vec{E} \quad \text{没有阻尼力}$$

没有磁场?

$$\frac{d\vec{j}_s}{dt} = \frac{n e^* e^{*2}}{m^*} \vec{E} \quad (\text{London 第一方程})$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\frac{\partial}{\partial t} (\nabla \times \vec{j}_s) = \frac{n e^* e^{*2}}{m^*} \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

初始条件 $\vec{j}_s = 0 \quad \vec{B} = 0$

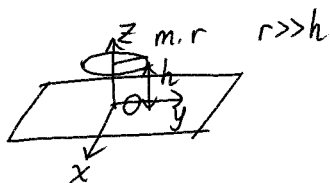
$$\nabla \times \vec{j}_s = -\frac{n e^* e^{*2}}{m^*} \vec{B} \quad (\text{London 第二方程})$$

*: Cooper 对

$$m^* = 2m$$

$$e^* = 2e$$

超导体像法



$$F = \frac{\mu_0 I}{2\pi} \frac{I}{2h} \cdot 2\pi R = mg$$

$$\Rightarrow I = \sqrt{\frac{2mgh}{\mu_0 R}}$$

$$F = \frac{\mu_0 R}{2h} \frac{2mgh_0}{\mu_0 R} \quad h = h_0 + \delta$$

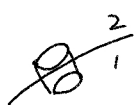
$$= mg \left(1 - \frac{\delta}{h_0}\right)$$

$$m\ddot{\delta} = F - mg = -\frac{mg}{h_0}\delta$$

$$\ddot{\delta} + \frac{g}{h_0}\delta = 0$$

$$T = 2\pi \sqrt{\frac{h_0}{g}}$$

边值关系

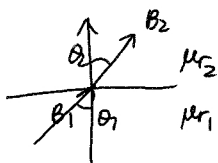
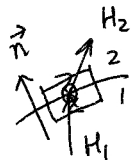


$$\nabla \cdot \mathbf{B} = 0 \leftrightarrow B_{1n} = B_{2n}$$

$$\nabla \times \mathbf{H} = \mathbf{j}_0 \quad \text{传导电流}$$

$$\vec{n} \times (\vec{H}_2 - \vec{H}_1) = \mathbf{j}_0$$

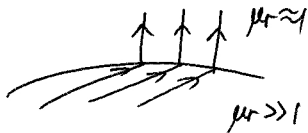
$$\mathbf{j}_0 = 0 \Rightarrow H_{1t} = H_{2t}$$



$$B_1 \cos \theta_1 = B_2 \cos \theta_2$$

$$\left. \begin{aligned} B_1 \cos \theta_1 &= B_2 \cos \theta_2 \\ \frac{B_1}{\mu_1} \sin \theta_1 &= \frac{B_2}{\mu_2} \sin \theta_2 \quad (\mathbf{j}_0 = 0) \end{aligned} \right\}$$

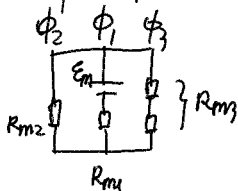
$$\frac{\tan \theta_1}{\mu_1} = \frac{\tan \theta_2}{\mu_2}$$



磁路

$$\Phi_m (R_m + r_m) = \mathcal{E}_m$$

$$R_m = \frac{l}{\mu S}$$



$$U_{m3} = \frac{(R_{m2} \parallel R_{m3}) \mathcal{E}_m}{(R_{m2} \parallel R_{m3}) + R_{m1}} = \phi_3 R_{m3}$$

介质中磁场的基本方程:

$$\begin{cases} \nabla \cdot \mathbf{B} = 0 \\ \nabla \times \mathbf{H} = \mathbf{j}_0 \end{cases} + \begin{array}{l} \text{边值关系} \\ \text{本构方程} \end{array}$$

一. 各向同性均匀介质充满空间

$$\mathbf{B} = \mu_0 \mu_r \mathbf{H} = \mu_0 (\mathbf{H} + \mathbf{M})$$

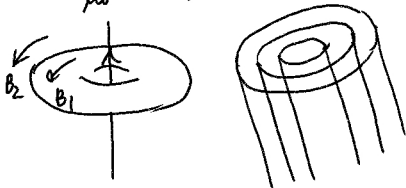
$$\nabla \times \mathbf{B} = \mu_0 \mu_r \mathbf{j}_0$$

$$\mathbf{j}_0 + \mathbf{j}' = \mu_r \mathbf{j}_0$$

$$\begin{cases} \nabla \cdot \mathbf{H} = 0 \\ \nabla \times \mathbf{H} = \mathbf{j}_0 \end{cases} \quad \mathbf{H} \text{ 与真空中相同}$$

二. 介质界面与 \mathbf{B} 平行

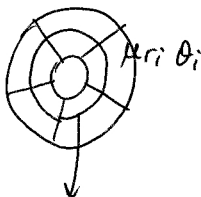
$$\mathbf{H} = \frac{\mathbf{B}_0}{\mu_0} \quad \mathbf{B} = \mu_r \mathbf{B}_0 \quad \mathbf{H} \text{ 不变}$$



三. 介质界面与 \mathbf{B} 垂直
 \mathbf{B} 与 \mathbf{B}_0 差一常数

$$\oint \frac{\mathbf{B}}{\mu_0 \mu_r} \cdot d\mathbf{l} = \Sigma I_0 \Rightarrow \mathbf{B}$$

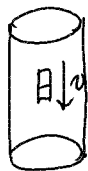
磁化电流仅出现在有传导
 电流出现的地方



$$\frac{B r}{\mu_0} \sum_{i=1}^n \frac{\theta_i}{\mu_r i} = I_0$$

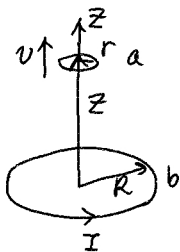
$$B = \frac{\mu_0 I_0}{r \sum_{i=1}^n \frac{\theta_i}{\mu_r i}}$$

电磁感应



$$\frac{\epsilon^2}{R} = mgv$$

e.g.



$$R \gg r$$

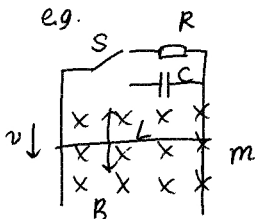
$$z \gg R$$

$$B = \frac{\mu_0 I}{2} \frac{R^2}{(R^2 + z^2)^{3/2}} \approx \frac{\mu_0 I}{2} \frac{R^2}{z^3}$$

$$\phi = \frac{\mu_0 I}{2} \frac{R^2}{z^3} \pi r^2$$

$$|\epsilon| = \left| \frac{d\phi}{dt} \right| = \frac{\mu_0 I R^2 \pi r^2}{2} \frac{-3}{z^4} v$$

e.g.



(1) 接 R

$$\epsilon = BLv$$

$$F = BIL$$

$$mg - F = m \frac{dv}{dt}$$

$$\epsilon = IR$$

$$\Rightarrow mg - \frac{B^2 L^2 v}{R} = m \dot{v}$$

$$v = \frac{mgR}{B^2 L^2} \left(1 - e^{-\frac{B^2 L^2}{mR} t} \right)$$

(2)

$$q = Cu$$

$$u = \epsilon = BLv$$

$$\dot{q} = I \quad mg - BL^2 C \dot{v} = m \dot{v}$$

$$F = BIL$$

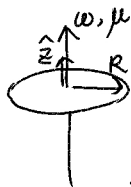
$$mg - F = m \dot{v}$$

$$\dot{v} = \frac{mg}{m + B^2 L^2 C}$$

$$\vec{E} = -\nabla u - \frac{\partial \vec{A}}{\partial t}$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} = -\nabla \times \frac{\partial \vec{A}}{\partial t}$$

eg. 均匀带电圆盘匀加速旋转



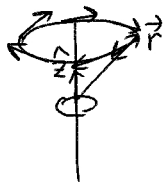
$$q, \omega = \alpha t$$

$$\mu = \int_0^R \frac{2\pi r dr \sigma r \omega \pi r^2}{5}$$

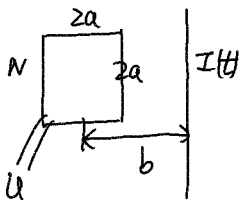
$$= 2\pi^2 \sigma \omega \frac{1}{5} R^5$$

远处: $A = \frac{\mu_0}{4\pi} \frac{\vec{\mu} \times \vec{r}}{r^3}$

$$E = -\frac{\partial A}{\partial t} = -\frac{\mu_0}{4\pi r^3} \frac{2}{5} \pi^2 R^5 \sigma \alpha \hat{z} \times \vec{r}$$



脉冲电流的测量



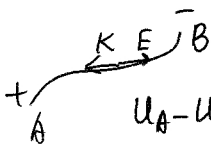
$$B = \frac{\mu_0 I(t)}{2\pi r}$$

$$U = N \frac{d\phi}{dt}$$

$$\phi = \int_{b-a}^{b+a} \frac{\mu_0 I(t)}{2\pi} \frac{2a dr}{r}$$

$$= \frac{\mu_0 I(t) a}{\pi} \ln\left(\frac{b+a}{b-a}\right)$$

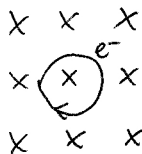
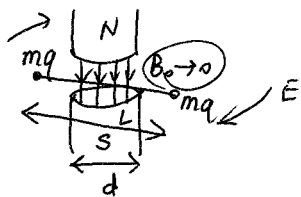
$$U = \frac{N\mu_0 a}{\pi} \ln\left(\frac{b+a}{b-a}\right) \frac{dI}{dt}$$



$$U_A - U_B = -\int_B^A \vec{E} \cdot d\vec{l}$$

$$= \int_B^A K \cdot d\vec{l}$$

电磁场具有角动量:



$$\left\{ \begin{aligned} \frac{mv^2}{R} &= e v B \\ \frac{1}{2} m v^2 &= \mu = \text{Const} \end{aligned} \right.$$

$$\Rightarrow \frac{1}{2m} \left(\frac{eBR}{B} \right)^2 = \frac{e^2}{2m} B R^2 = \mu$$

$$B_1 R_1^2 = B_2 R_2^2$$

$$1 \quad 1 \quad 3 \quad \frac{1}{\sqrt{3}}$$

$$E \pi L = - \frac{dB}{dt} \cdot \pi \frac{d^2}{4}$$

$$2qE \cdot \frac{1}{2} L = 2m \left(\frac{L}{2} \right)^2 \frac{d\omega}{dt}$$

$$\dot{\omega} = - \frac{q d^2}{2mL^2} \dot{B}$$

$$\omega = \frac{q d^2}{2mL} B_0 \quad (\text{只与 } \Delta B \text{ 有关})$$

$$2m \frac{L}{2} \omega = J = \frac{q d^2}{2} B_0$$

$$S = E \times H$$

$$g = \frac{S}{c^2}$$

$$l = r \times g$$

互感

$$\Phi_{21} = M_{21} I_1$$

磁通定义



$$\begin{cases} \Phi_{21} = M_{21} I_1 \\ \Phi_{12} = M_{12} I_2 \end{cases}$$

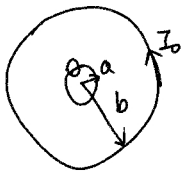
互感系数的对称性

$$M_{21} = M_{12} = \frac{\mu_0}{4\pi} \oint_{L_1} \oint_{L_2} \frac{d\vec{l}_1 \cdot d\vec{l}_2}{r}$$

互感系数的计算

利用 $M_{12} = M_{21}$ 简化问题

e.g.



$$a \ll b$$

b 有 a 中磁场

近似为常数

$$\Phi = \pi a^2 \frac{\mu_0 I}{2b}$$

$$M = \frac{\mu_0 \pi a^2}{2b}$$

e.g. 互绕螺线管

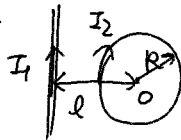
$$S, l, N_1, N_2$$

$$\mu_0 \frac{N_1}{l} I_1 \cdot N_2 S = \Phi$$

$$M = \frac{\mu_0 S N_1 N_2}{l}$$

$$= \mu_0 n_1 n_2 V$$

e.g.



$$B = \frac{\mu_0 I}{2\pi r}$$

$$\Phi_{21} = M I_1$$

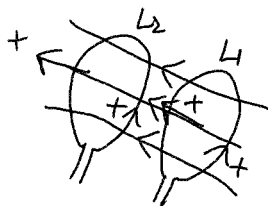
互感电动势

$$\begin{cases} \mathcal{E}_1 = -M_{12} \frac{dI_2}{dt} & \text{电动势定义} \\ \mathcal{E}_2 = -M_{21} \frac{dI_1}{dt} & \text{实际测量} \end{cases}$$

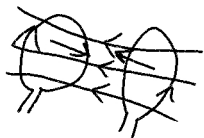
磁能定义

$$W = \iiint_V w dV = \pm M I_1 I_2 + \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2$$

M 何时为正
何时为负



$M > 0$



$M < 0$

取决于线圈中
电流正方向的定义

自感

$$\phi = LI \quad \text{磁通定义} \quad \varepsilon = -L \frac{dI}{dt} \quad \text{电动势定义}$$

$$L = M_{11} = \frac{\mu_0}{4\pi} \oint \oint \frac{d\vec{l}_1 \cdot d\vec{l}_2}{r} \quad L \text{ 总大于 } 0$$

电磁惯量

可能发散 导线的曲线模型失效 必须考虑粗细

导线内有一定的电流分布, 与不同层电流相对应的磁通不同
此时自感是个平均值

磁能定义 (功能)

$$\frac{1}{2} LI^2 = \iiint_V w_m dV = \frac{1}{2} \iiint_V \vec{B} \cdot \vec{H} dV$$

$$L = \frac{W_m}{\frac{1}{2} I^2}$$

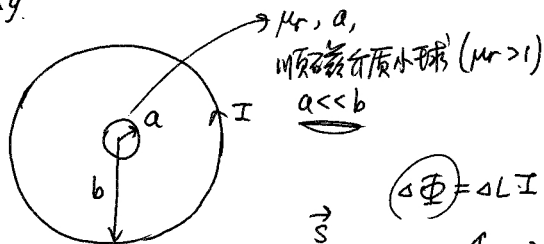
e.g.

理想单螺线管

$$\mu \frac{N}{l} I \cdot N \cdot S = \phi$$

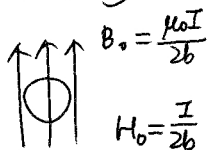
$$L = \mu \frac{N^2 S}{l} = \mu n^2 V$$

e.g.



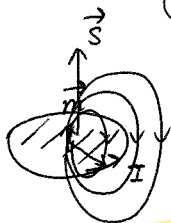
(1) 求小球 M

(2) 求 ΔL



$$\Delta \Phi = \Delta L I$$

$$\vec{m} = \frac{4}{3} \pi a^3 M = \frac{2\pi a^3 I}{b} \frac{\mu_r - 1}{\mu_r + 2}$$



$$A = \frac{\mu_0 \vec{m} \times \vec{r}}{4\pi r^3} \quad (a \ll b) \quad \vec{r} \perp \vec{m}$$

$$\iint_S \vec{B} \cdot d\vec{S} = \oint_{\partial S} \vec{A} \cdot d\vec{l}$$

$$H' = -\frac{M}{3} \quad B' = \frac{2}{3} \mu_0 M$$

$$= \mu_0 \frac{\pi a^3 I}{b^2} \frac{\mu_r - 1}{\mu_r + 2}$$

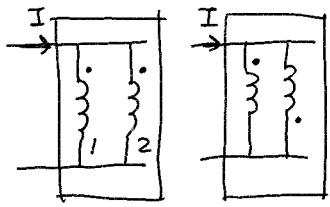
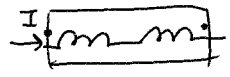
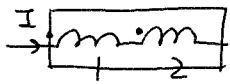
$$\begin{cases} H = H_0 + H' & \mu_0 (H' + M) = B' \\ M = H (\mu_r - 1) \end{cases}$$

$$\Delta L = \mu_0 \frac{\pi a^3}{b^2} \frac{\mu_r - 1}{\mu_r + 2}$$

$$\Rightarrow H = \frac{3}{\mu_r + 2} H_0$$

$$M = \frac{3(\mu_r - 1)}{\mu_r + 2} \frac{I}{2b}$$

线圈的串并联



同名

电动势定义

$$\mathcal{E} = -\left(L_1 \frac{dI_1}{dt} + M \frac{dI_2}{dt} \right)$$

$$= -\left(L_2 \frac{dI_2}{dt} + M \frac{dI_1}{dt} \right)$$

$$\frac{dI}{dt} = \frac{dI_1}{dt} + \frac{dI_2}{dt}$$

$$\Rightarrow \mathcal{E} = -L' \frac{dI}{dt} \quad L' = \frac{4L_2 - M^2}{4 + L_2 - 2M}$$

异名

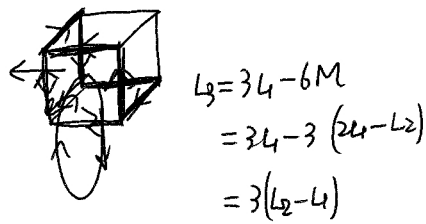
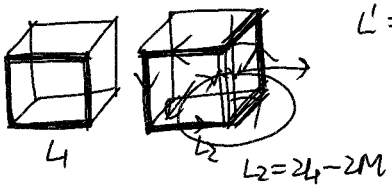
$$L' = \frac{4L_2 - (M)^2}{4 + L_2 - 2(-M)} = \frac{4L_2 - M^2}{4 + L_2 + 2M}$$

$$\phi = \phi_1 + \phi_2$$

$$\phi = (L_1 + L_2 + 2M) I$$

$$\phi = (L_1 + L_2 - 2M) I$$

磁通定义

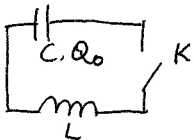


无耦合 $M=0$
理想耦合 $M = \sqrt{L_1 L_2}$

暂态过程

RL

$$\tau = \frac{L}{R}$$



RC

$$\tau = RC$$

$$I = -\frac{dq}{dt}$$

$$-L \frac{dI}{dt} + \frac{q}{C} = 0$$

RLC

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$\ddot{q} + \frac{1}{LC} q = 0$$

磁能

载流线圈的磁能

已考虑电源

$$\sum_i \frac{1}{2} L_i I_i^2 + \frac{1}{2} \sum_{ij} M_{ij} I_i I_j$$

载流线圈在外磁场中的势能
 I_1

↓
也是由电流产生
 I_2

$$W_2 = M I_1 I_2 = I_1 \phi_1$$

均匀外场 $W = I_1 \vec{B} \cdot \vec{S} = \vec{m} \cdot \vec{B}$

磁能属于磁场

$$w_m = \frac{1}{2} \mathbf{B} \cdot \mathbf{H}$$

$$W_e = \frac{1}{2} \sum_{k=1}^N Q_k U_k \leftrightarrow W_m = \frac{1}{2} \sum_{k=1}^N I_k \phi_k$$

$$\frac{1}{2} \sum_k U_k \int_{V_k} \rho dV$$

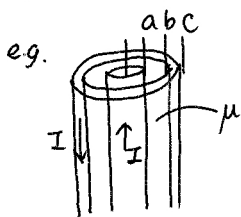
$$\frac{1}{2} \sum_k I_k \oint_{L_k} \vec{A} \cdot d\vec{l}$$

$$U \leftrightarrow I$$

$$Q \leftrightarrow \phi$$

$$W_e = \frac{1}{2} \int_{V'} \rho u dV \leftrightarrow W_e = \frac{1}{2} \int_{V'} \vec{A} \cdot \vec{j} dV$$

用自感、互感的磁能定义求 L, M



$$L = \frac{2W_m}{I^2}$$

$$0 \leq r \leq a$$

$$H = \frac{\pi r^2}{\pi a^2} \cdot I \frac{1}{2\pi r} = \frac{Ir}{2\pi a^2}$$

$$w = \frac{1}{2} \mu_0 H^2 = \frac{\mu_0 I^2}{2 \cdot 4\pi^2 a^4} r^2$$

磁介质存在时的磁能

介质改变 LSM

电源存在过程中的做功

$$dA = d\left(\frac{1}{2}\mu_0 H^2\right) + \underbrace{\mu_0 \vec{H} \cdot d\vec{M}}_{\text{磁化功}}$$

宏观磁能

对于线性无损耗介质

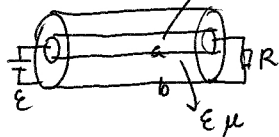
$$\text{可定义磁化能 } \vec{H} \cdot d\vec{M} = \vec{M} \cdot d\vec{H}$$

$$\mu_0 \vec{H} \cdot d\vec{M} = d\left(\frac{1}{2}\mu_0 \vec{H} \cdot \vec{M}\right)$$

$$W_m = \frac{1}{2}\mu_0 H^2 + \frac{1}{2}\mu_0 \vec{H} \cdot \vec{M}$$

$$= \frac{1}{2} \vec{B} \cdot \vec{H}$$

e.g.



不仅内部有电流
表面还有电荷

$$I = \frac{\epsilon}{R}$$

视作均匀分布

$$D = \frac{\lambda}{2\pi r}$$

$$E = \frac{\lambda}{2\pi \epsilon \epsilon_r r}$$

$$H = \frac{I}{2\pi r}$$

$$B = \frac{\mu_0 \mu_r I}{2\pi r}$$

$$U = \frac{\lambda}{2\pi \epsilon \epsilon_r} \ln \frac{b}{a} = \epsilon$$

↓
λ

载流线圈有源

三“线圈” 如基本粒子的固有磁矩

无源 无热效应 无感应电动势

区分

小磁矩在外磁场中的受力

$$W = -\vec{m} \cdot \vec{B}$$

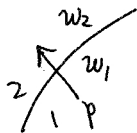
$$F = -(\nabla W)$$

$$F = \nabla (m \cdot B) = m \times (\underbrace{\nabla \times B}_0) + B \times (\nabla \times m) + (\underbrace{m \cdot \nabla}_0) B + (B \cdot \nabla) m$$

源在别处
m处无电流

固定 \vec{m} $F = (\vec{m} \cdot \nabla) \vec{B}$

$$M = \vec{m} \times \vec{B}$$

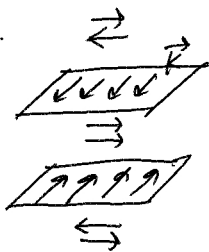


$$P_{1 \rightarrow 2} = w_1 - w_2$$

电流平面受力

倾向使磁场能量增加

e.g.



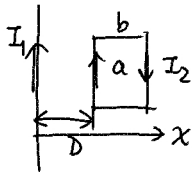
$\circ \uparrow f \downarrow \nabla w$
 $\mu_0 K$

\circ

$$f = -\nabla w \quad (\text{力}) \frac{1}{2} \mu_0 K^2 = \frac{\Delta F}{\Delta S}$$

$$= -\frac{1}{2} \frac{(\mu_0 K)^2}{\mu_0} \delta S$$

e.g.



作用力与有源还是无源无关

$$W = \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 + M I_1 I_2$$

不变 > 0

$$F = \left(\frac{\partial W}{\partial D} \right)_{I_2} = \frac{\mu_0 a}{2\pi} I_1 I_2 \frac{1}{1 + \frac{b}{D}} \left(-\frac{b}{D^2} \right) = -\frac{\mu_0 a}{2\pi} I_1 I_2 \frac{b}{D^2 + Db}$$

引力

有源 保持 I_2 不变 (要考虑电源做功)

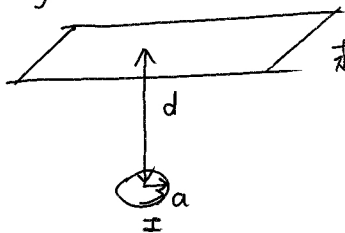
$$F = -\left(\frac{\partial W}{\partial D} \right)_{\phi} = \text{同. 引力}$$

$I \leftrightarrow U$

无源. 保持 ϕ_2 不变

$\phi \leftrightarrow Q$

e.g.



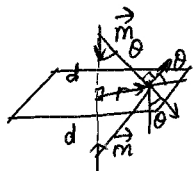
超导平面

$$F = \int_0^{+\infty} f(a) 2\pi r dr$$

$$= \frac{9}{8} \mu_0 I^2 d^2 a^4 \pi \int_0^{+\infty} \frac{r^2 2r}{(r^2+d^2)^5} dr$$

$$= \frac{3}{32} \frac{\mu_0 I^2 a^4 \pi}{d^4} \quad \parallel \quad \frac{1}{12d^6}$$

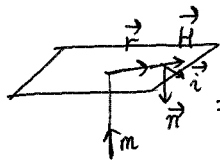
(1) 平面上的感应电流



$$\vec{B} = \frac{\mu_0 m}{4\pi R^3} (2\cos\theta \vec{e}_r + \sin\theta \vec{e}_\theta)$$

$$B = \frac{\mu_0 m}{4\pi (r^2+d^2)^{3/2}} \cdot \frac{rd}{r^2+d^2} \times 2$$

$$H = B/\mu_0 = \frac{3I\pi a^2}{2\pi} \frac{rd}{(r^2+d^2)^{5/2}} \hat{r}$$



$$\vec{F} = \vec{n} \times (\vec{H} - 0)$$

$$= \frac{3I}{2} \frac{a^2 rd}{(r^2+d^2)^{5/2}} \underbrace{\vec{n} \times \hat{r}}_{\hat{\theta}}$$

(2) 平面受力 $f = W_m = \frac{1}{2} \mu_0 H^2$ 斥力

$$\frac{1}{2} \mu_0 \left(\frac{3I}{2} \frac{a^2 rd}{(r^2+d^2)^{5/2}} \right)^2$$

圆环受力.

$\vec{F} =$

$$\frac{3\mu_0}{4\pi r^4} [(\vec{m}_1 \cdot \hat{r}) \vec{m}_2 + (\vec{m}_2 \cdot \hat{r}) \vec{m}_1 + (\vec{m}_1 \cdot \vec{m}_2) \hat{r} - 5(\vec{m}_1 \cdot \hat{r})(\vec{m}_2 \cdot \hat{r}) \hat{r}]$$

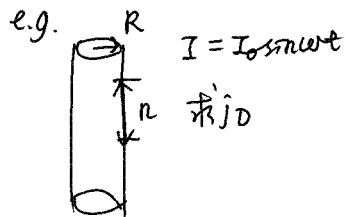
$$\parallel$$

$$\frac{3\mu_0}{64\pi d^4} (-m^2 - m^2 - m^2 + 5m^2) \hat{r}$$

$$= \frac{3}{32} \frac{\mu_0 m^2}{\pi d^4} \hat{r}$$

斥力.

$$\begin{cases} \nabla \cdot D = \rho \\ \nabla \times E = -\frac{\partial B}{\partial t} \\ \nabla \cdot B = 0 \\ \nabla \times H = j_0 + \underbrace{\frac{\partial D}{\partial t}}_{j_D} \end{cases}$$



只考虑一阶感应

$$B = \mu_0 n I_0 \sin \omega t$$

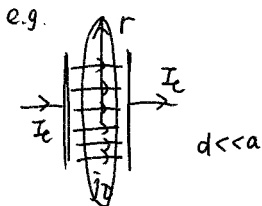
感应电场

$$E \cdot 2\pi r = -\pi r^2 \frac{\partial B}{\partial t}$$

$$\vec{E} = \begin{cases} -\frac{r}{2} \mu_0 n I_0 \omega \cos \omega t \vec{e}_\theta & (0 \leq r \leq R) \\ -\frac{R^2}{2r} \mu_0 n I_0 \omega \cos \omega t \vec{e}_\theta & (R < r) \end{cases}$$

$$j_D = \frac{\partial D}{\partial t} = \epsilon_0 \frac{\partial E}{\partial t}$$

$$= \begin{cases} \frac{1}{2} r \epsilon_0 \mu_0 n I_0 \omega^2 \sin \omega t \vec{e}_\theta & 0 \leq r \leq R \\ \frac{R^2}{2r} \epsilon_0 \mu_0 n I_0 \omega^2 \sin \omega t \vec{e}_\theta & r > R \end{cases}$$



$$E d = U = \frac{Q}{C} \quad \frac{\partial E}{\partial t} = \frac{1}{dC} I_c$$

$$j_D = \frac{\epsilon_0}{dC} I_c = \frac{I_c}{S}$$

\downarrow
 $\frac{\epsilon_0 S}{d}$

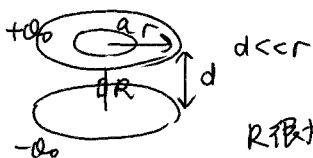
$$H = \begin{cases} \frac{\pi a^2 j_D}{2\pi r} = \frac{I_c}{2\pi r} & r > a \\ \frac{\pi r^2 j_D}{2\pi r} = \frac{r I_c}{2\pi a^2} & r < a \end{cases}$$

就相当于只由 I_c

激发 $d \ll a$

可忽略

e.g.



$d \ll r$
 R 很大 d 很大
 忽略高阶项

$$B = \frac{r^2 - a^2}{r^2} \frac{Q_0 \mu_0}{2\pi a R C} e^{-\frac{t}{RC}}$$

(1) $U = \frac{Q}{C}$

$$U = IR$$

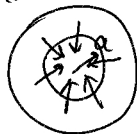
$$I = -\dot{Q}$$

$$-\dot{Q}R = \frac{1}{C}Q$$

$$\dot{Q} + \frac{1}{RC}Q = 0 \quad E = \frac{U}{d} = \frac{Q_0}{Cd} e^{-\frac{t}{RC}}$$

$$Q = Q_0 e^{-\frac{t}{RC}} \quad \dot{E} = \frac{Q_0}{\epsilon_0 \pi r^2} \left(-\frac{1}{RC}\right) e^{-\frac{t}{RC}}$$

(2)



$$I_a = \frac{r^2 - a^2}{r^2} I$$

(3) $\nabla \times H = j_0 + \frac{\partial D}{\partial t}$

$\frac{\partial D}{\partial t} \uparrow \downarrow I$

$\frac{\partial D}{\partial t} \uparrow \downarrow I$

注意 j_0

注意方向

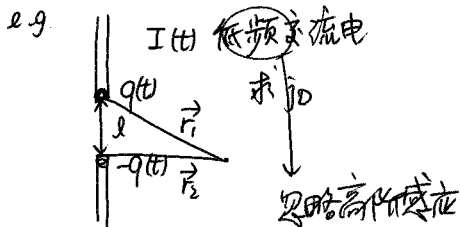
$$H \cdot 2\pi a = I + \frac{1}{\epsilon_0} a^2 \frac{\partial Q_0}{\epsilon_0 \pi r^2} \left(-\frac{1}{RC}\right) e^{-\frac{t}{RC}}$$

$$= \frac{r^2 - a^2}{r^2} \frac{Q_0}{RC} e^{-\frac{t}{RC}}$$

似稳条件

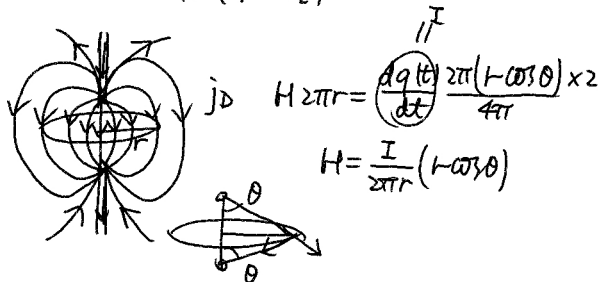
毕萨定律仍成立

位移电流对磁场贡献近似为0



$$\vec{E}(t) \approx \frac{q(t)}{4\pi\epsilon_0} \left(\frac{\vec{r}_1}{r_1^3} - \frac{\vec{r}_2}{r_2^3} \right)$$

$$\vec{j}_D = \epsilon_0 \frac{\partial \vec{E}(t)}{\partial t} = \frac{1}{4\pi} \left(\frac{\vec{r}_1}{r_1^3} - \frac{\vec{r}_2}{r_2^3} \right) \frac{dq(t)}{dt}$$



由 B-S 定律计算 $H = \frac{I}{2\pi r} (1-\cos\theta)$

新相当于只考虑传导电流即可

电磁波

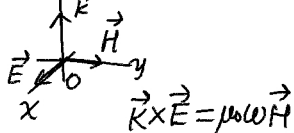
e.g.

真空中电磁波

$$\begin{cases} \frac{\partial^2 E}{\partial t^2} - c^2 \nabla^2 E = 0 \\ \frac{\partial^2 B}{\partial t^2} - c^2 \nabla^2 B = 0 \end{cases} \quad c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

$$\vec{E} = E_0 \cos(\omega \sqrt{\mu_0 \epsilon_0} z - \omega t) \vec{e}_x$$

$$(1) \quad \vec{k} = \omega \sqrt{\mu_0 \epsilon_0} \vec{e}_z$$



$$\vec{k} \times \vec{E} = \mu_0 \omega \vec{H}$$

$$\text{平面波 } u = u_0 e^{-i(\omega t - \vec{k} \cdot \vec{r})}$$

$$\vec{H} = \sqrt{\frac{\epsilon_0}{\mu_0}} E_0 \cos(\omega \sqrt{\mu_0 \epsilon_0} z - \omega t) \vec{e}_y$$

$$\begin{cases} \nabla \cdot \vec{E} = 0 & \nabla \cdot \vec{H} = 0 \\ \nabla \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t} \\ \nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{cases} \Rightarrow \begin{cases} \vec{k} \cdot \vec{E} = \vec{k} \cdot \vec{H} = 0 \\ \vec{k} \times \vec{E} = \mu_0 \omega \vec{H} \\ \vec{k} \times \vec{H} = -\epsilon_0 \omega \vec{E} \end{cases} \quad (2)$$

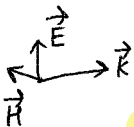
$$\omega = \frac{1}{2} (\epsilon_0 E^2 + \mu_0 H^2)$$

$$= \epsilon_0 E_0^2 \cos^2(\omega \sqrt{\mu_0 \epsilon_0} z - \omega t)$$

$$\langle \omega \rangle = \frac{1}{2} \epsilon_0 E_0^2$$

介质中 $\mu_0, \epsilon_0 \rightarrow \mu_0 \mu_r, \epsilon_0 \epsilon_r$

(3)



$$\sqrt{\epsilon_0 \epsilon_r} E_0 = \sqrt{\mu_0 \mu_r} H_0$$

$$S = \vec{E} \times \vec{H}$$

$$v = \frac{1}{\sqrt{\epsilon_0 \epsilon_r \mu_0 \mu_r}} = \frac{c}{\sqrt{\epsilon_r \mu_r}}$$

$$= \sqrt{\frac{\epsilon_0}{\mu_0}} E_0^2 \cos^2(\omega \sqrt{\mu_0 \epsilon_0} z - \omega t) \vec{e}_z$$

$$\frac{E_0}{B_0} = \frac{c}{n}$$

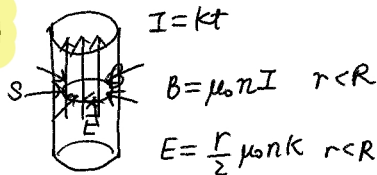
$$\sqrt{\frac{\omega}{\sigma \mu_0}} = \frac{E_0}{B_0} \quad \text{良导体}$$

$$\langle S \rangle = \frac{1}{2} \sqrt{\frac{\epsilon_0}{\mu_0}} E_0^2 \vec{e}_z$$

电磁波的能量与动量

e.g. 螺线管

$$\vec{S} = \vec{E} \times \vec{H} \quad w = \frac{1}{2}(\epsilon E^2 + \mu B^2)$$



$$I = k t$$

$$B = \mu_0 n I \quad r < R$$

$$E = \frac{r}{2} \mu_0 n k \quad r < R$$

$$S = \frac{E \times B}{\mu_0} = -\frac{r}{2} \mu_0 n^2 k^2 t \hat{e}_r \quad r < R$$

W_e 不变

$W_m \uparrow$

$$-\frac{\partial w}{\partial t} = \nabla \cdot \vec{S} + \vec{j} \cdot \vec{E}$$

对电流做功

$$\vec{S} = w \vec{v}$$

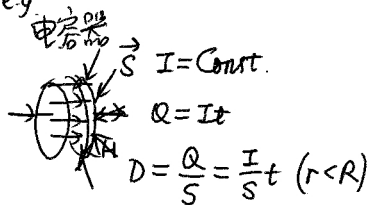
真空中 $\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$

平面电磁波

$$\begin{cases} \vec{E} = E_0 \cos(kx - \omega t) \hat{j} \\ \vec{B} = B_0 \cos(kx - \omega t) \hat{k} \end{cases}$$

$$\vec{S} = \frac{E_0 B_0}{\mu_0} \cos^2(kx - \omega t) \hat{i}$$

e.g.



$$I = \text{const.}$$

$$Q = I t$$

$$D = \frac{Q}{S} = \frac{I}{S} t \quad (r < R)$$

$$H = \frac{r}{2} \frac{I}{S} \quad (r < R)$$

定义波的强度 $I = \langle S \rangle = \frac{E_0 B_0}{2\mu_0}$

$$\langle \cos^2(kx - \omega t) \rangle = \frac{1}{2}$$

时间平均值

动量密度 $\vec{g} = \frac{1}{c^2} \vec{S}$

角 $\vec{l} = \vec{r} \times \vec{g}$



$$S = \frac{1}{\epsilon} D \times H = -\frac{1}{\epsilon_0} \frac{I^2}{8\pi^2 R^4} r \hat{e}_r \quad r < R$$

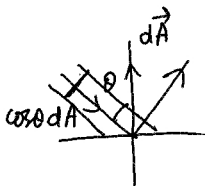
W_m 不变

$W_e \uparrow$

$P = I A$

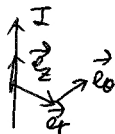
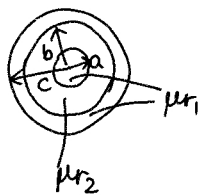
$$\frac{S_{\lambda} \downarrow \uparrow S_{R}}{\hline}$$

$$\frac{1}{c^2} (\vec{S}_{\lambda} - \vec{S}_{R}) = \Delta p$$



$$d\vec{F} = - \frac{(1+R)\bar{S} \cos\theta}{c^2} \underbrace{\cos\theta}_{\cos^2\theta} d\vec{A}$$

例4



$r < a$

$$H \cdot 2\pi r = \frac{r^2}{a^2} I$$

$$\vec{H} = \frac{r}{2\pi a^2} I \vec{e}_\theta$$

$$\vec{B} = \mu_0 \mu_1 \frac{r}{2\pi a^2} I \vec{e}_\theta$$

$$\vec{M} = (\mu_1 - 1) \vec{H} = (\mu_1 - 1) \frac{rI}{2\pi a^2} \vec{e}_\theta$$

$a < r < b$

$$\vec{H} = \frac{I}{2\pi r} \vec{e}_\theta$$

$$\vec{B} = \mu_0 \mu_2 \frac{I}{2\pi r} \vec{e}_\theta$$

$$\vec{M} = (\mu_2 - 1) \frac{I}{2\pi r} \vec{e}_\theta$$

$b < r < c$

$$\vec{H} = \frac{1}{2\pi r} \left(1 - \frac{r^2 - b^2}{c^2 - b^2}\right) I \vec{e}_\theta$$

$B \sim M \sim$

$r > c$

$$\vec{H} = 0 \quad B = M = 0$$

$$W_m = \frac{1}{2} B \cdot H = \frac{1}{2} \mu_0 \mu_r H^2$$

$$W_1 = \int_0^a \frac{1}{2} \mu_0 \mu_1 \left(\frac{I}{2\pi a^2}\right)^2 r^2 \cdot 2\pi r dr$$

$$= \frac{1}{2} \mu_0 \mu_1 \frac{I^2}{2\pi a^4} \cdot \frac{1}{4} a^4$$

$$= \frac{\mu_0 \mu_1}{16\pi} I^2 l$$

$$W_2 = \int_a^b \frac{1}{2} \mu_0 \mu_2 \left(\frac{I}{2\pi r}\right)^2 \cdot 2\pi r dr$$

$$= \frac{1}{2} \mu_0 \mu_2 \frac{I^2}{2\pi} l \ln\left(\frac{b}{a}\right)$$

$$W_3 = \int_b^c \frac{1}{2} \mu_0 \mu_1 \left(\frac{I}{2\pi r}\right)^2 \left(\frac{c^2 - r^2}{c^2 - b^2}\right)^2$$

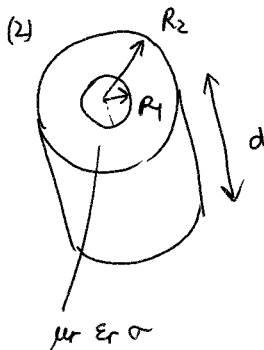
$$= \frac{1}{2} \mu_0 \mu_1 \frac{I^2 l}{2\pi} \frac{1}{(c^2 - b^2)^2} \int_b^c \left(\frac{c^4}{r} - 2c^2 r + r^3\right) dr$$

$$\left(c^4 \ln\left(\frac{c}{b}\right) - c^2(c^2 - b^2) + \frac{1}{4}(c^4 - b^4) \right)$$

$$= \frac{\mu_0 \mu_1 I^2 l}{4\pi} \left(\frac{c^4}{(c^2 - b^2)^2} \ln\left(\frac{c}{b}\right) - \frac{c^2}{c^2 - b^2} + \frac{1}{4} \frac{c^4 + b^4}{c^2 - b^2} \right)$$

$$W_4 = 0$$

$$L = \frac{2W}{I^2 l} = \frac{\mu_0 \mu r_1}{8\pi} + \mu_0 \mu r_2 \frac{1}{2\pi} \ln\left(\frac{b}{a}\right) + \frac{\mu_0 \mu r_1}{2\pi} \left(\frac{e^2}{(c^2 - b^2)^2} \ln\left(\frac{c}{b}\right) - \frac{c^2}{c^2 - b^2} + \frac{c^2 + b^2}{c^2 - b^2} \right)$$



$$H = \frac{I}{2\pi r}$$

$$W = \int_{R_1}^{R_2} \frac{1}{2} \mu_0 \mu r \left(\frac{I}{2\pi r} \right)^2 d \cdot 2\pi r dr$$

$$= \frac{\mu_0 \mu r}{4\pi} I^2 d \ln\left(\frac{R_2}{R_1}\right)$$

$$L = \frac{\mu_0 \mu r d}{2\pi} \ln\left(\frac{R_2}{R_1}\right)$$

$$E = \frac{Q/d}{2\pi \epsilon_0 \epsilon_r r}$$

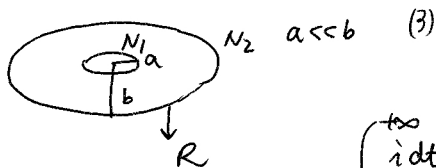
$$R = \int_{R_1}^{R_2} \frac{dr}{d \cdot 2\pi r \cdot \sigma}$$

$$U = \int_{R_1}^{R_2} \frac{Q/d}{2\pi \epsilon_0 \epsilon_r r} dr = \frac{Q/d}{2\pi \epsilon_0 \epsilon_r} \ln\left(\frac{R_2}{R_1}\right)$$

$$= \frac{1}{2\pi \sigma d} \ln\left(\frac{R_2}{R_1}\right)$$

$$\Rightarrow C = \frac{Q}{U} = \frac{2\pi \epsilon_0 \epsilon_r d}{\ln\left(\frac{R_2}{R_1}\right)}$$

$$\begin{cases} RC = \frac{\epsilon_0 \epsilon_r}{\sigma} \\ L/R = \mu_0 \mu \sigma \\ LC = \mu_0 \mu r \epsilon_0 \epsilon_r \end{cases}$$



$$i = \mathcal{E}/R$$

$$\int_0^{\infty} i dt = \frac{1}{R} \int_0^{\infty} \mathcal{E} dt$$

$x = vt$

(1)

$$M = M_{12}$$

$$\phi_{12} = M_{12} I_2$$

$$\phi_{12} = N_1 \pi a^2 \frac{\mu_0 N_2 I_2}{2b}$$

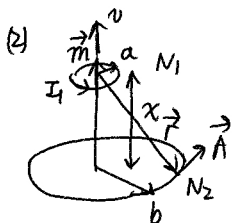
$$\Rightarrow M = \frac{\pi a^2}{2b} \mu_0 N_1 N_2$$

$$\int_0^{\infty} \mu_0 I_1 \pi a^2 b \frac{x}{(x^2 + b^2)^2} dx N_1 N_2$$

$$= \mu_0 I_1 \pi a^2 b \frac{1}{2} \frac{1}{b} N_1 N_2$$

$$Q = \frac{\mu_0 I_1 \pi a^2 N_1 N_2}{2Rb}$$

$$(4) \vec{B} = \frac{\mu_0 N_2 I_2}{2} \frac{b^2}{(x^2 + b^2)^{3/2}} (-\vec{e}_z)$$



$$W = -m \cdot B$$

$$F = -\nabla(m \cdot B) = (m \cdot \nabla) B$$

$$\phi_2 = \oint_{L_2} \vec{A} \cdot d\vec{l} = \frac{\mu_0 I_1 \pi a^2}{2} \frac{b}{x^2 + b^2} N_1 N_2 = -N_1 I_1 \pi a^2 \frac{d}{dx} \vec{B}$$

$$= N_1 I_1 \pi a^2 \frac{\mu_0 N_2 I_2}{2} \frac{b^2 3x}{(x^2 + b^2)^{5/2}}$$

$$\mathcal{E} = -\frac{d\phi_2}{dt} = -\frac{\mu_0 I_1 \pi a^2 b}{2} \left(-\frac{bx}{(x^2 + b^2)^2} \right) \cdot v N_1 N_2 = mg \quad (x=h)$$

$$I_2 = \frac{2mg(h^2 + b^2)^{5/2}}{N_1 N_2 \mu_0 I_1 \pi a^2 b^2 3h}$$

$$2h > b$$

(5)

$$F(h+\delta) = \frac{1}{2} M_1 M_2 I_1 I_2 3\pi a^2 b^2 \mu_0 \frac{h+\delta}{((h+\delta)^2 + b^2)^{5/2}}$$

$$= mg \left(1 - \frac{4h^2 - b^2}{h(h^2 + b^2)} \delta \right) \left(1 + \left(\frac{1}{h} - \frac{5h}{h^2 + b^2} \right) \delta \right)$$

$$\Rightarrow T = 2\pi \sqrt{\frac{h(h^2 + b^2)}{(4h^2 - b^2)g}} \quad 2h > b \text{ 时 可 稳定 平衡}$$

